

Chapter 5

Input/Output

- 5.1 Principles of I/O hardware
- 5.2 Principles of I/O software
- 5.3 I/O software layers
- 5.4 Disks
- 5.5 Clocks
- 5.7 Graphical user interfaces
- 5.8 Network terminals

INPUT/OUTPUT

- OS
 - control all the computer's I/O devices
 - issue commands to the devices, catch interrupts, and handle errors
 - provide an **interface** between the devices and the rest of the system that is **simple and easy to use**
 - the interface should be device independence

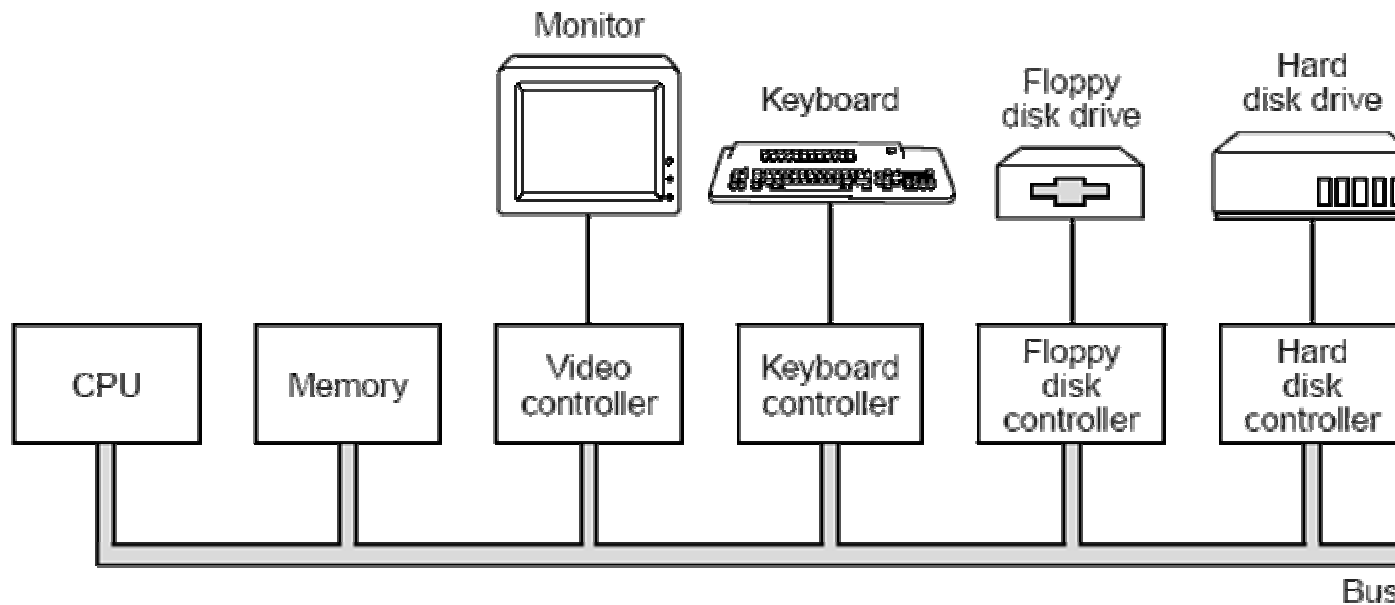
Principles of I/O Hardware

Some typical
device, network,
and bus data
rates

Device	Data rate
Keyboard	10 bytes/sec
Mouse	100 bytes/sec
56K modem	7 KB/sec
Telephone channel	8 KB/sec
Dual ISDN lines	16 KB/sec
Laser printer	100 KB/sec
Scanner	400 KB/sec
Classic Ethernet	1.25 MB/sec
USB (Universal Serial Bus)	1.5 MB/sec
Digital camcorder	4 MB/sec
IDE disk	5 MB/sec
40x CD-ROM	6 MB/sec
Fast Ethernet	12.5 MB/sec
ISA bus	16.7 MB/sec
EIDE (ATA-2) disk	16.7 MB/sec
FireWire (IEEE 1394)	50 MB/sec
XGA Monitor	60 MB/sec
SONET OC-12 network	78 MB/sec
SCSI Ultra 2 disk	80 MB/sec
Gigabit Ethernet	125 MB/sec
Ultrium tape	320 MB/sec
PCI bus	528 MB/sec
Sun Gigaplane XB backplane	20 GB/sec

Device Controllers

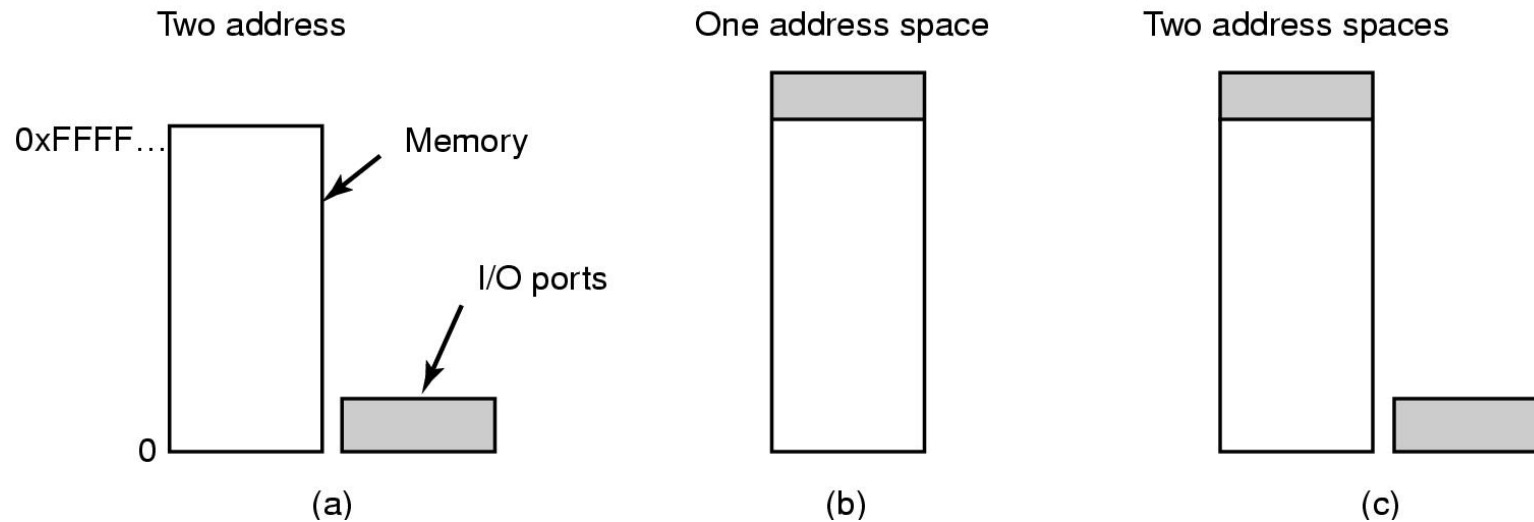
- **I/O devices have components:**
 - mechanical component
 - electronic component
- **The electronic component is the device controller**
 - may be able to handle multiple devices



Device Controller's Tasks

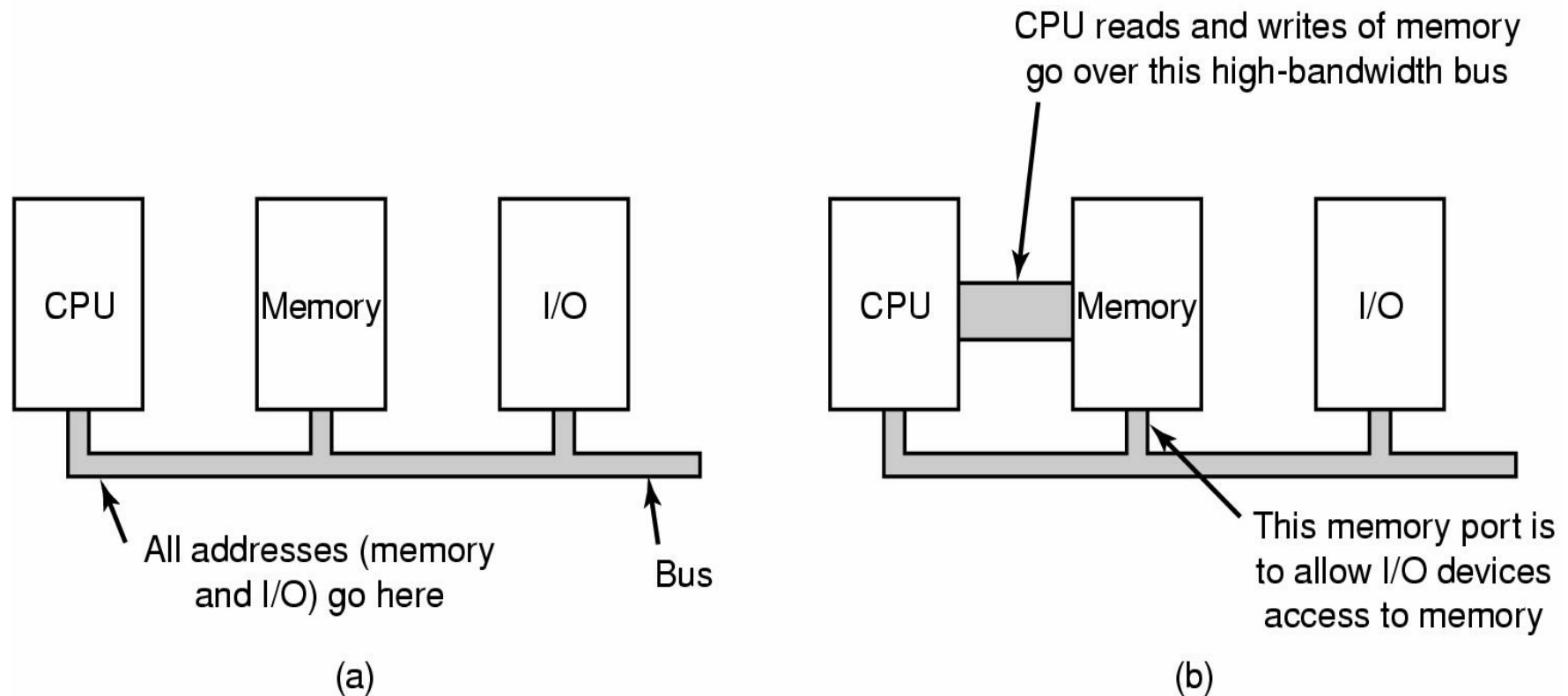
- **Convert serial bit stream to block of bytes of character**
- **Perform error correction as necessary**
 - **checksum, parity and etc.**
- **Make data available to main memory**
 - **CPU reads and writes the controller's registers to know states and deliver commands**
 - **data buffer is used to transfer data**

Memory-Mapped I/O (1)



- Separate I/O and memory space
- Memory-mapped I/O
- Hybrid

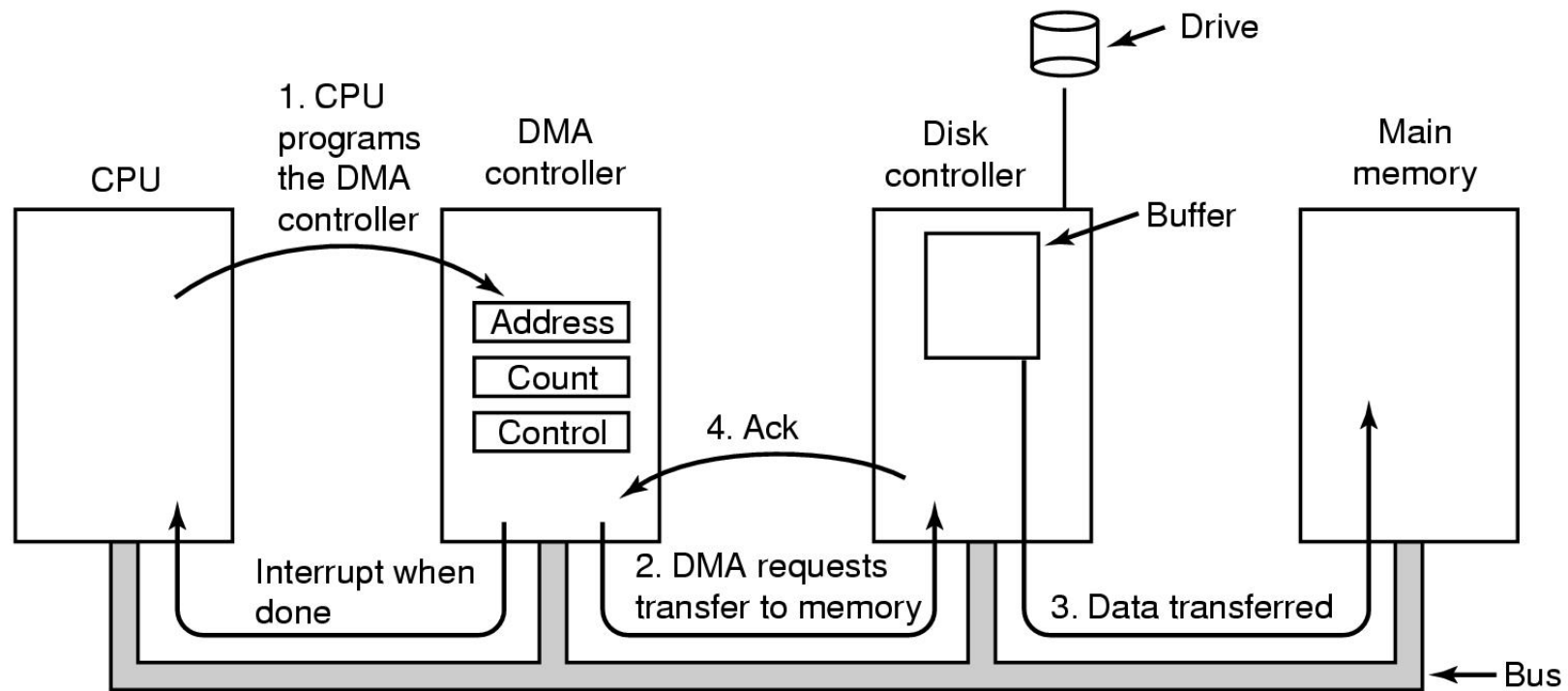
Memory-Mapped I/O (2)



(a) A single-bus architecture

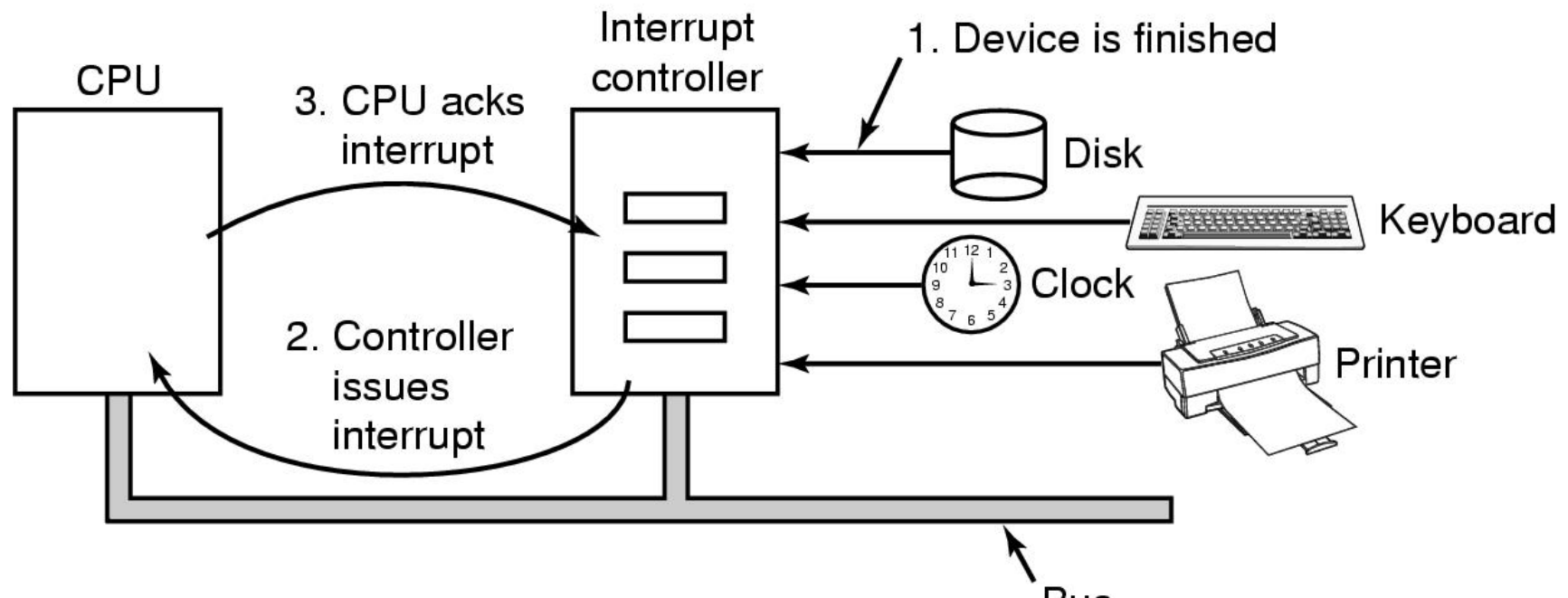
(b) A dual-bus memory architecture

Direct Memory Access (DMA)



Operation of a DMA transfer

Interrupts Revisited



How interrupts happens. Connections between devices and interrupt controller actually use interrupt lines on the bus rather than dedicated wires

Interrupts Revisited

- Check if an interrupt is pending after each instruction's execution
 - store program counter and PSW, then jump to interrupt vector
- A pipeline or superscalar CPU's PC doesn't mean the next instruction to execute but to fetch

Interrupts Revisited

- **Precise interrupt**
 - The PC is saved in a known place
 - All instructions before the one pointed to by the PC have fully executed
 - No instruction beyond the one pointed to by the PC has been executed
 - The execution state of the instruction pointed to by the PC is known
- **Imprecise interrupt**

Principles of I/O Software

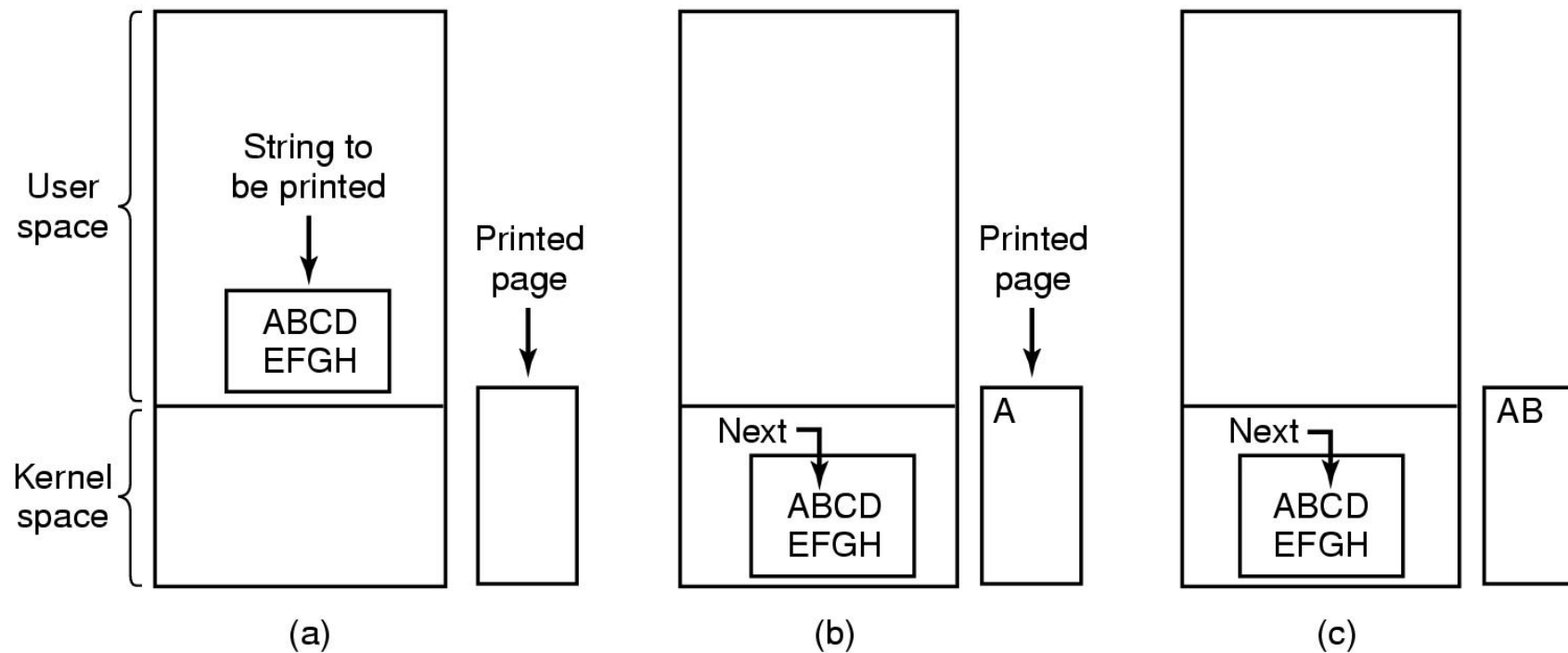
Goals of I/O Software (1)

- **Device independence**
 - programs can access any I/O device without specifying device in advance
 - (floppy, hard drive, or CD-ROM)
- **Uniform naming**
 - name of a file or device is a string or an integer
 - not depending on which device
- **Error handling**
 - handle as close to the hardware as possible
 - controller, driver, application

Goals of I/O Software (2)

- **Synchronous vs. asynchronous transfers**
 - blocked transfers vs. interrupt-driven
- **Buffering**
 - data coming off a device cannot be stored in final destination
- **Sharable vs. dedicated devices**
 - disks are sharable
 - tape drives would not be

Programmed I/O (1)



Steps in printing a string

Programmed I/O (2)

```
copy_from_user(buffer, p, count);          /* p is the kernel bufer */
for (i = 0; i < count; i++) {               /* loop on every character */
    while (*printer_status_reg != READY) ;   /* loop until ready */
    *printer_data_register = p[i];          /* output one character */
}
return_to_user();
```

**Writing a string to the printer using
programmed I/O**

Interrupt-Driven I/O

```
copy_from_user(buffer, p, count);  
enable_interrupts( );  
while (*printer_status_reg != READY) ;  
*printer_data_register = p[0];  
scheduler( );
```

(a)

```
if (count == 0) {  
    unblock_user( );  
} else {  
    *printer_data_register = p[i];  
    count = count - 1;  
    i = i + 1;  
}  
acknowledge_interrupt( );  
return_from_interrupt( );
```

(b)

- **Writing a string to the printer using interrupt-driven I/O**
 - Code executed when print system call is made
 - Interrupt service procedure

I/O Using DMA

```
copy_from_user(buffer, p, count);  
set_up_DMA_controller( );  
scheduler( );
```

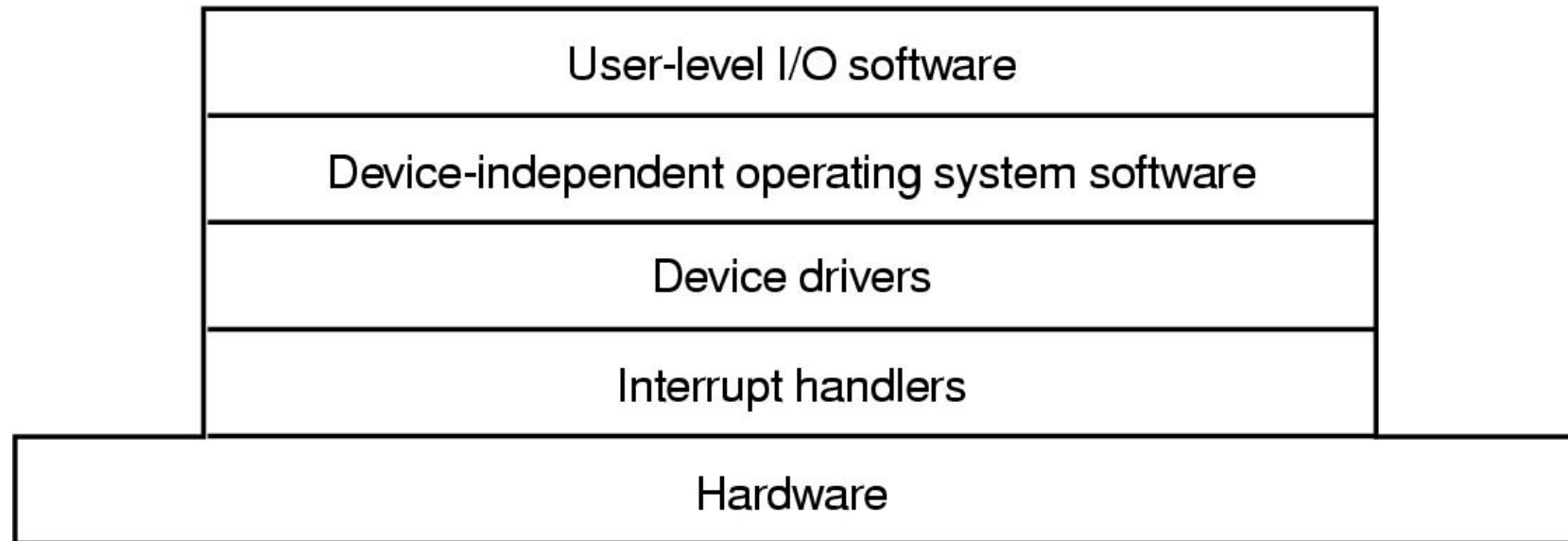
(a)

```
acknowledge_interrupt( );  
unblock_user( );  
return_from_interrupt( );
```

(b)

- **Printing a string using DMA**
 - code executed when the print system call is made
 - interrupt service procedure

I/O Software Layers



Layers of the I/O Software System

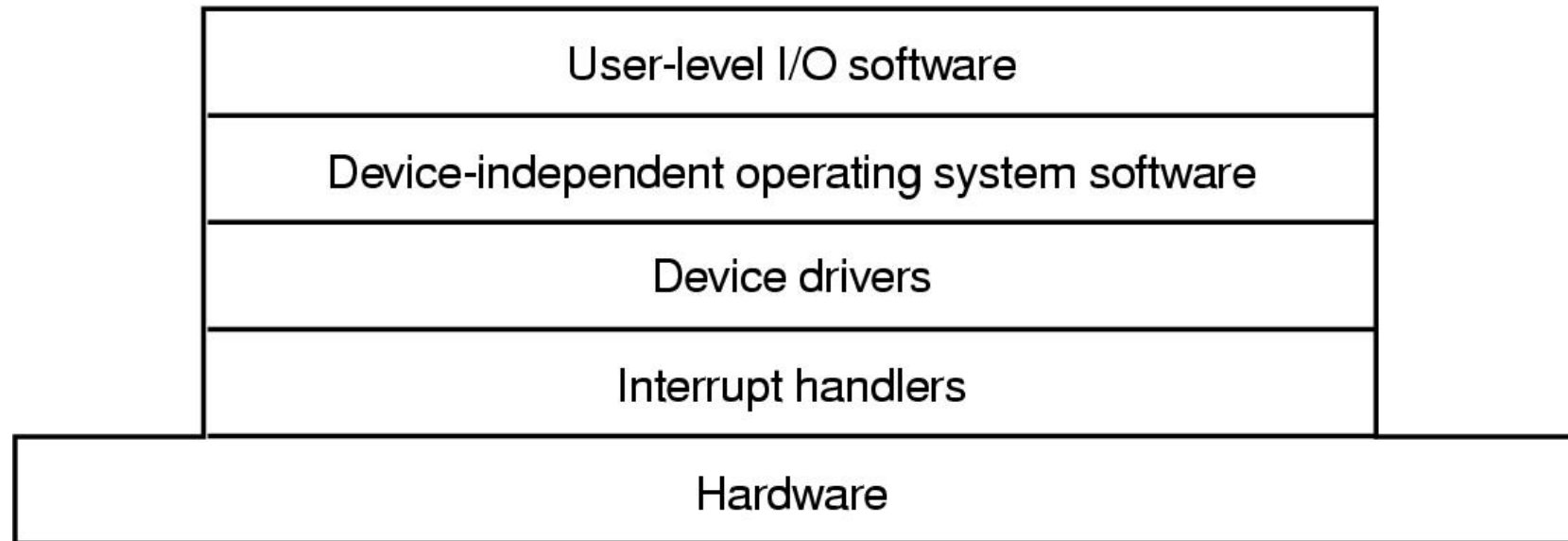
Interrupt Handlers (1)

- **Interrupt handlers are best hidden**
 - **block the driver starting an I/O operation until interrupt notifies of completion**
- **Interrupt procedure does its task**
 - **then unblocks driver that started it**
- **Steps must be performed in software after interrupt completed**

Interrupt Handlers (2)

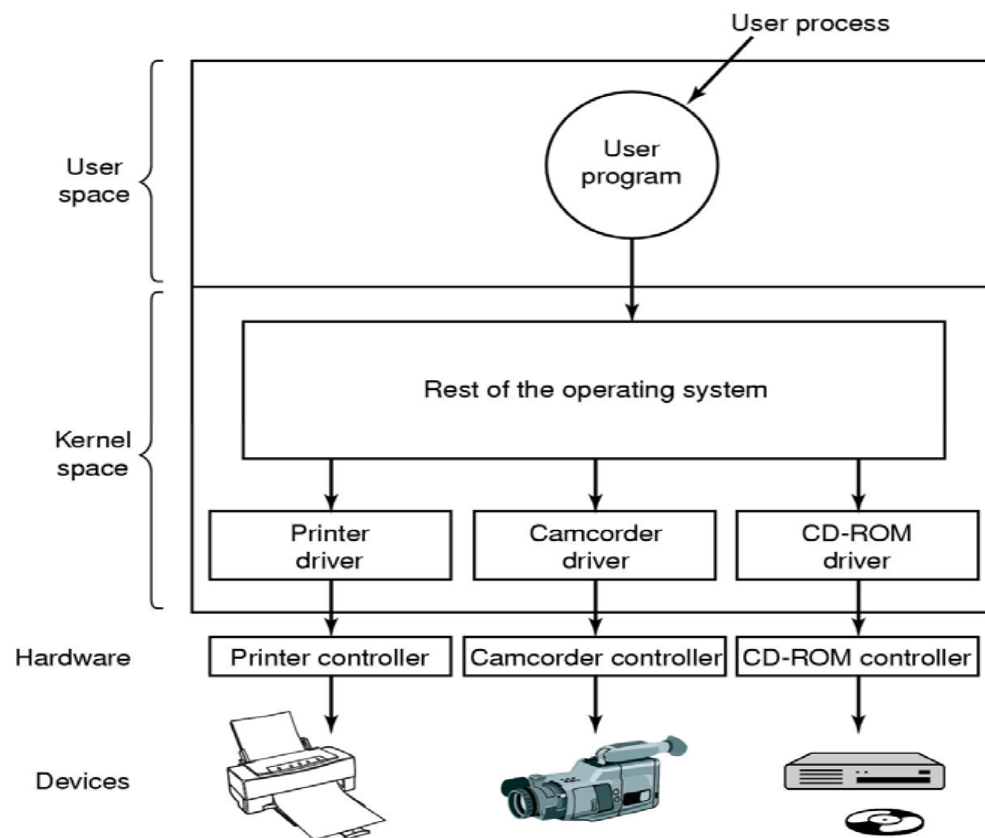
1. **Save registers not already saved by interrupt hardware**
2. **Set up context for interrupt service procedure**
3. **Set up stack for interrupt service procedure**
4. **Ack interrupt controller, reenable interrupts**
5. **Copy registers from where they saved to process table**
6. **Run service procedure**
7. **Set up MMU context for process to run next**
8. **Load new process' registers**
9. **Start running the new process**

I/O Software Layers



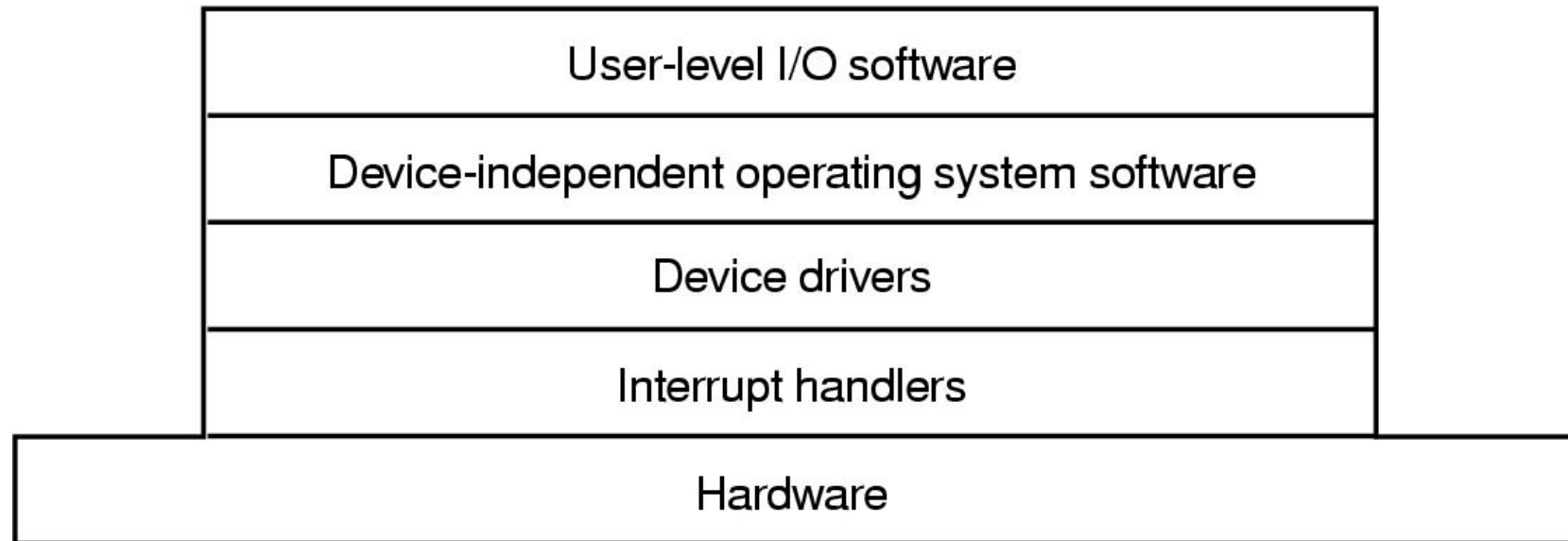
Layers of the I/O Software System

Device Drivers



- Logical position of device drivers is shown here
- Communications between drivers and device controllers goes over the bus

I/O Software Layers



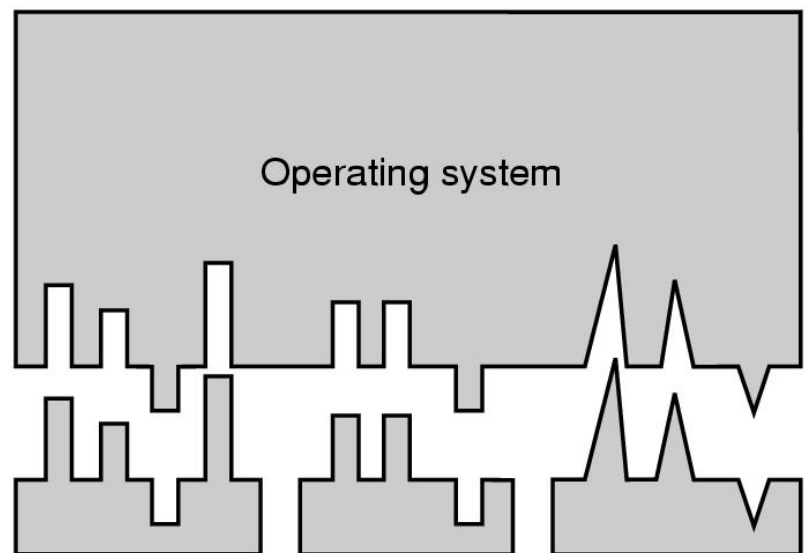
Layers of the I/O Software System

Device-Independent I/O Software

Uniform interfacing for device drivers
Buffering
Error reporting
Allocating and releasing dedicated devices
Providing a device-independent block size

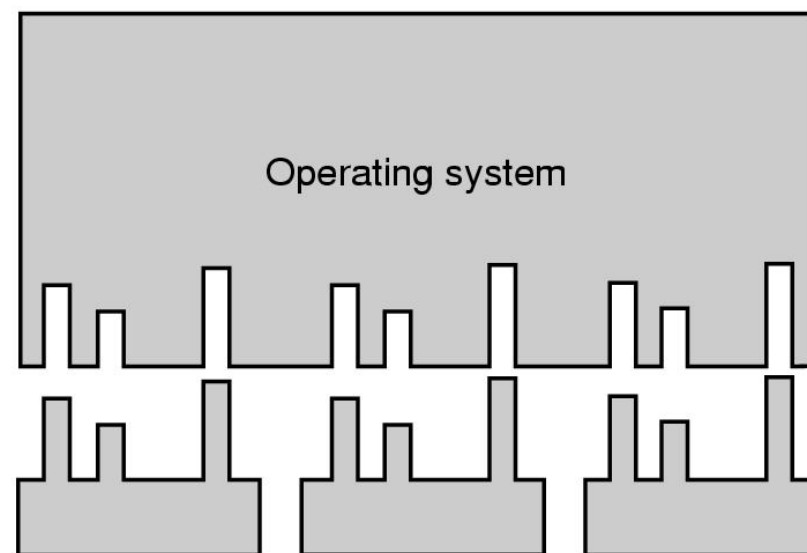
Functions of the device-independent I/O software

Uniform Interfacing for Device Drivers



Disk driver Printer driver Keyboard driver

(a)



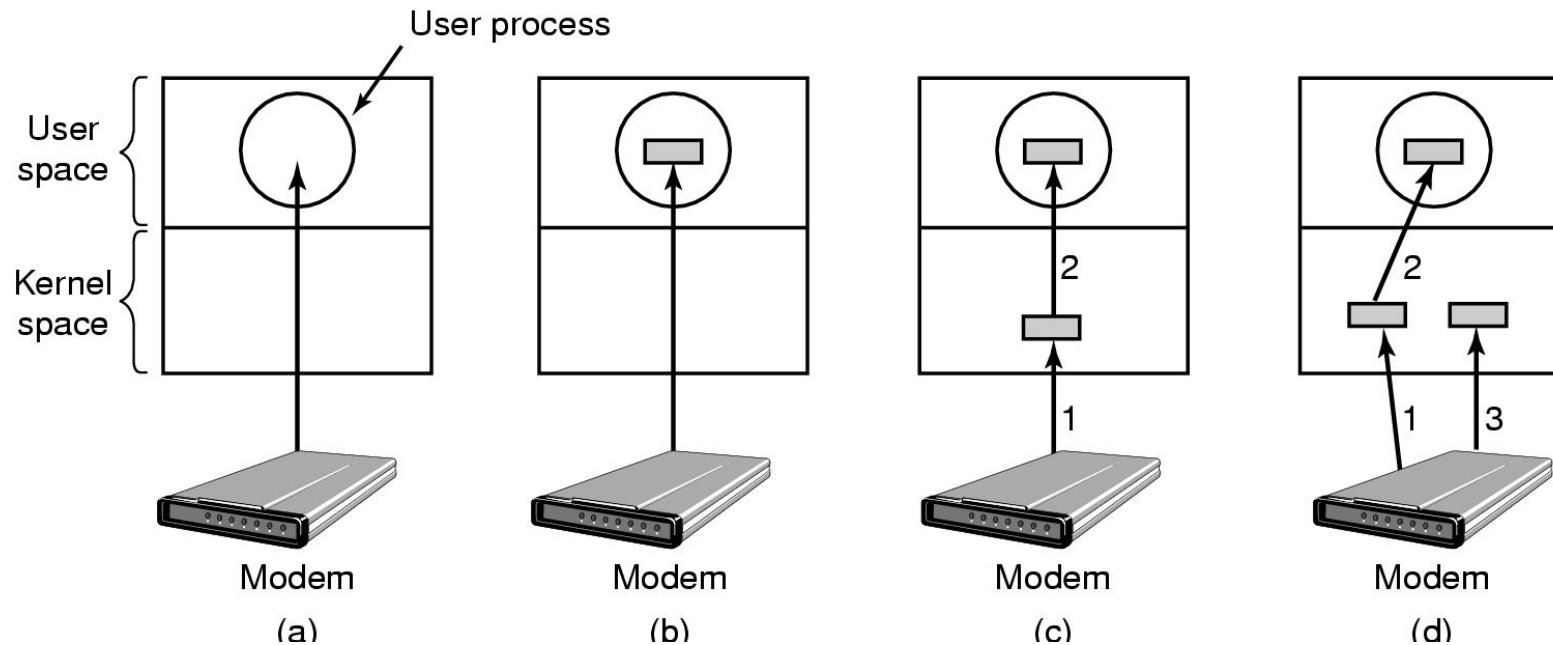
Disk driver Printer driver Keyboard driver

(b)

(a) Without a standard driver interface

(b) With a standard driver interface

Buffering



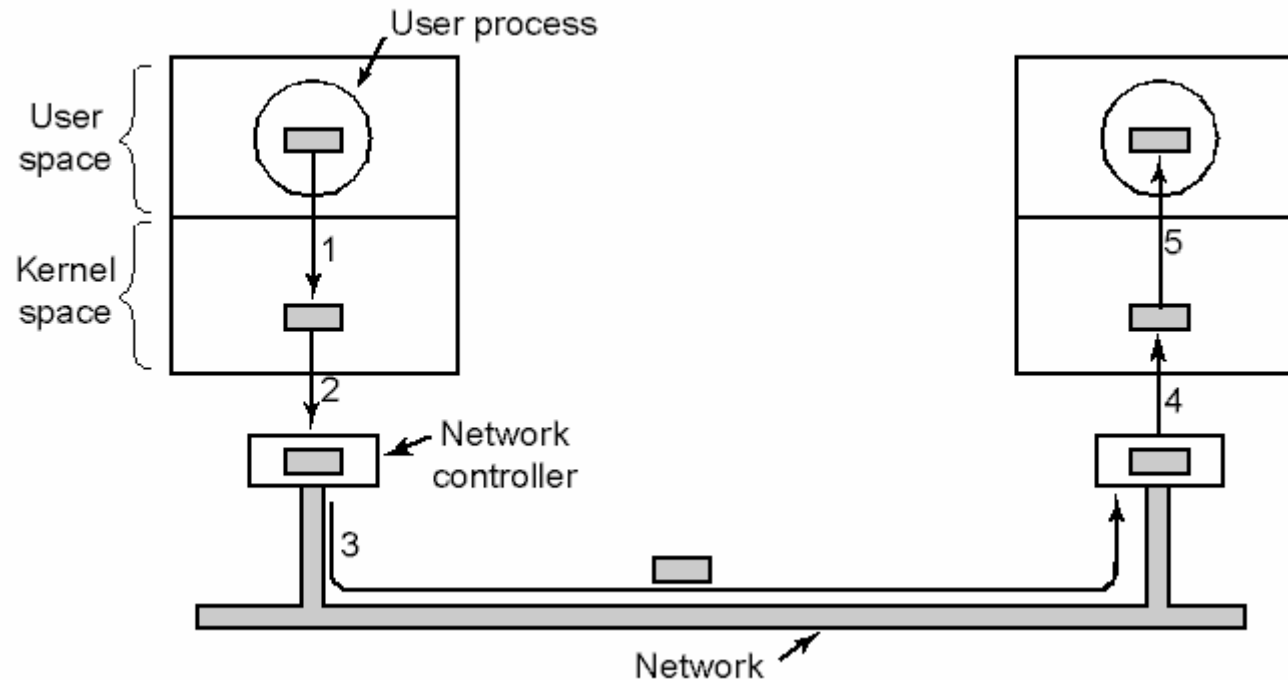
(a) Unbuffered input

(b) Buffering in user space

(c) Buffering in the kernel followed by copying to user space

(d) Double buffering in the kernel

Buffering



**Networking may involve many copies,
performance suffers**

Error Reporting

- **Errors are far more common in I/O than others**
 - **Programming errors**
 - ask for something impossible
 - invalid device, buffer address or other parameter
 - **I/O errors**
- **When error occurs**
 - **retry, ignore or quit**
 - **have the system call fail with an error code**
 - **terminate the system (blue screen)**

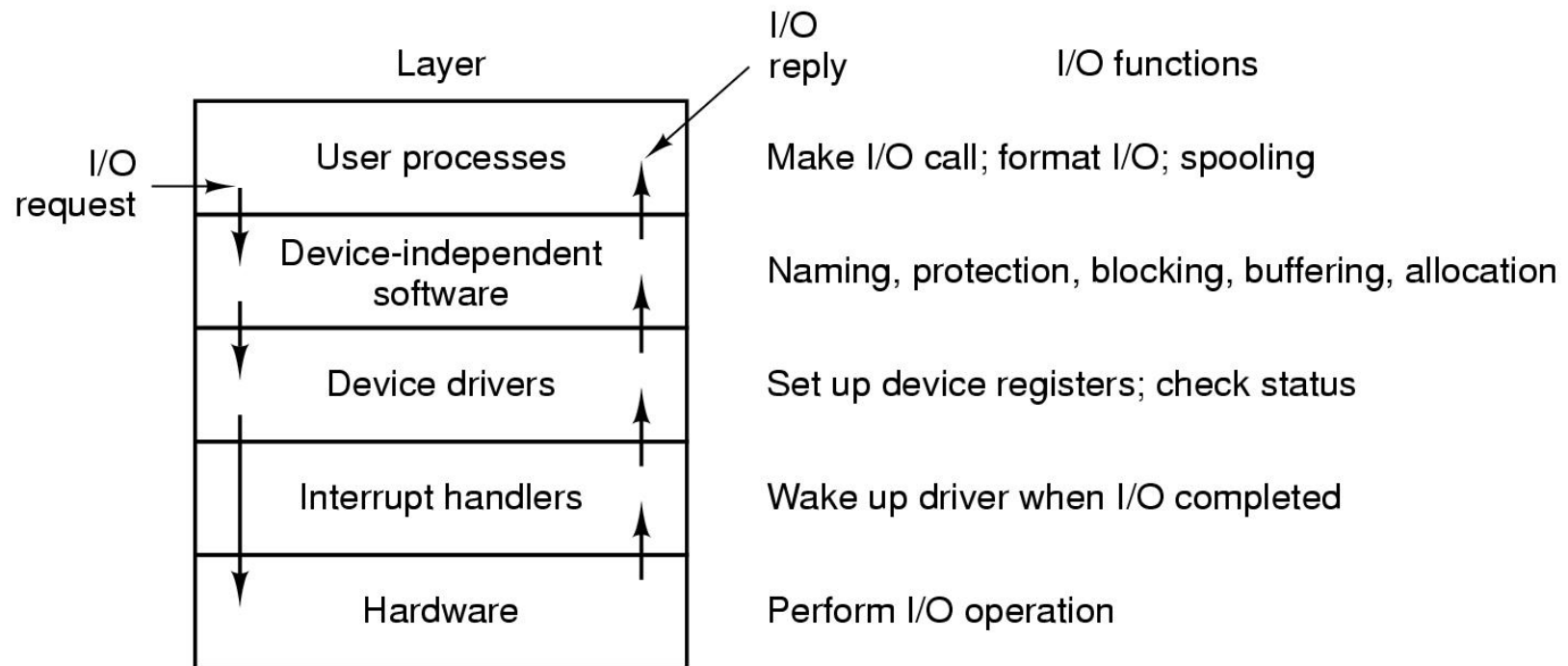
Other Functions

- **Allocating and releasing dedicated devices**
 - open, close
 - queue
- **Device-independent block size**
 - different disks may have different sector sizes
 - provide a uniform block size to higher layers

User-Space I/O Software

- **Link the I/O system call with the program**
 - `count = write(fd, buffer, nbytes);`
 - `printf("i = %d", i);`
- **Spooling to deal with dedicated devices**
 - create a special directory—**spooling directory**
 - create a special process—**daemon**, which is the only process having permission to use printer
 - put the files to be printed in the spooling directory

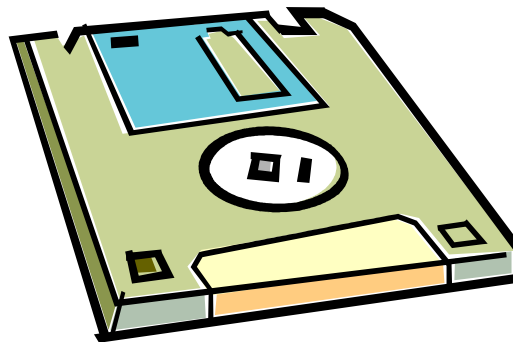
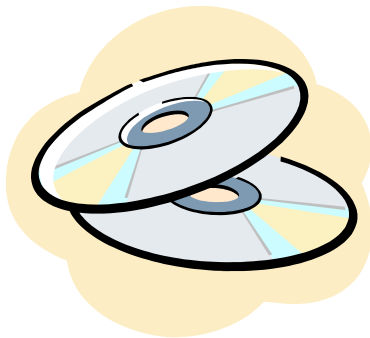
User-Space I/O Software



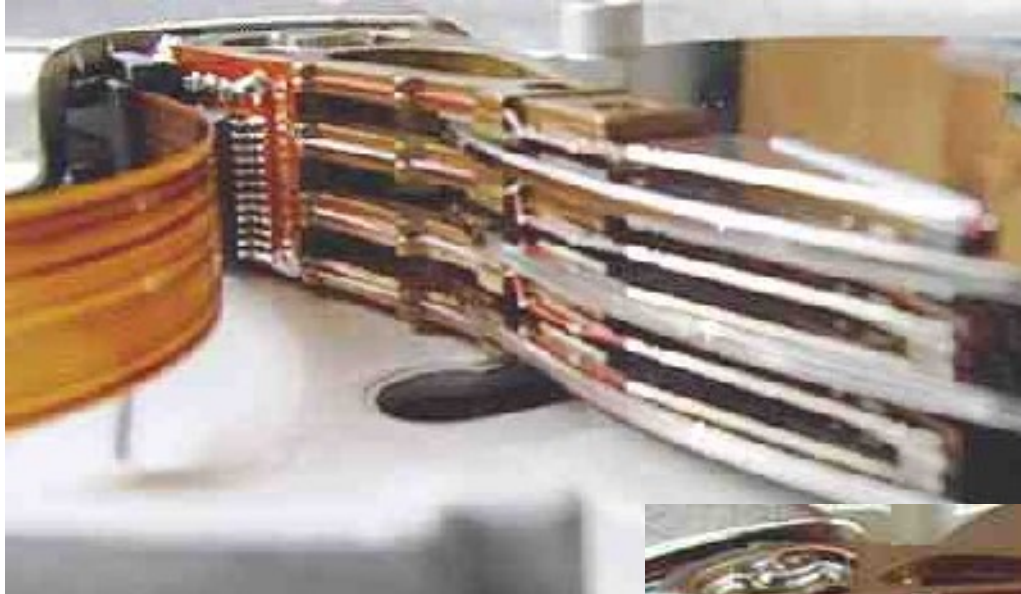
Layers of the I/O system and the main functions of each layer

Disks

- Magnetic disks
- RAID
- CD-ROMs
 - CD-R, CD-RW, DVD

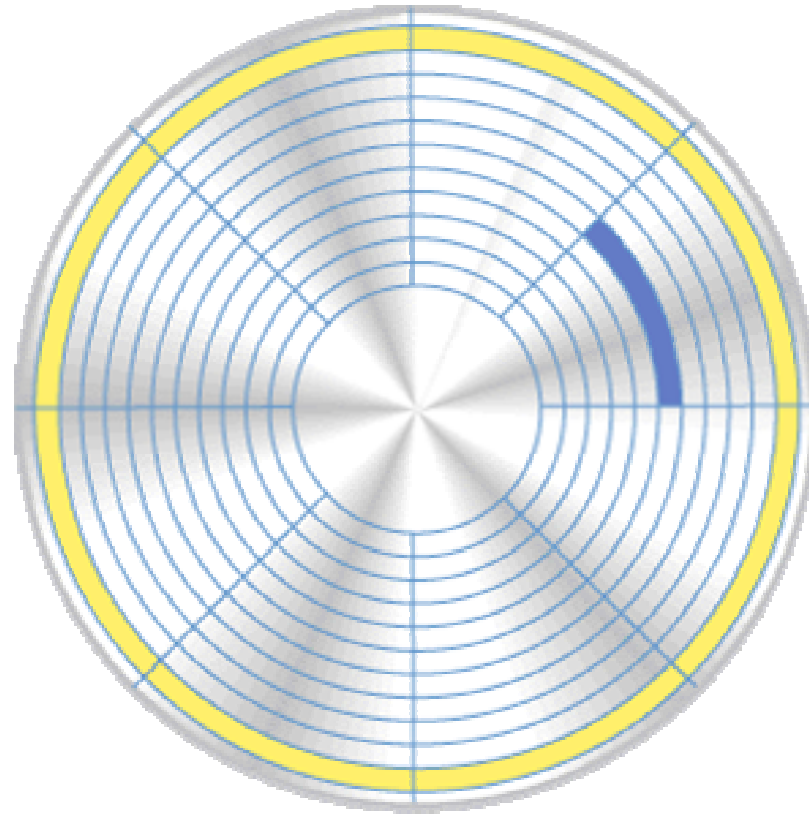


Hard Disks



Hard Disks

- Cylinders (x)
- Tracks (y)
- Sectors (z)
 - usually 512 Bytes
- Total capacity=?



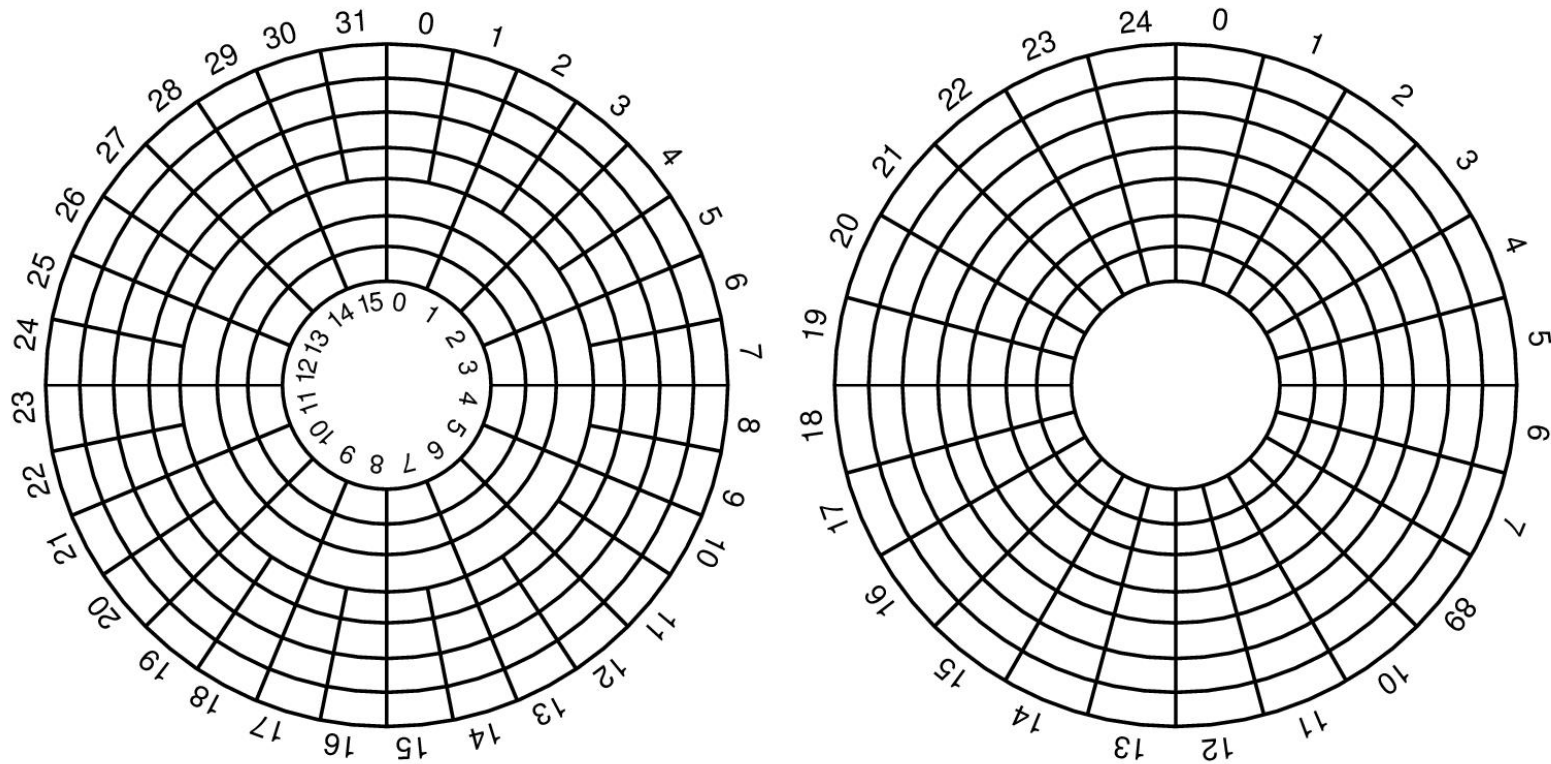
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Magnetic Disks

Parameter	IBM 360-KB floppy disk	WD 18300 hard disk
Number of cylinders	40	10601
Tracks per cylinder	2	12
Sectors per track	9	281 (avg)
Sectors per disk	720	35742000
Bytes per sector	512	512
Disk capacity	360 KB	18.3 GB
Seek time (adjacent cylinders)	6 msec	0.8 msec
Seek time (average case)	77 msec	6.9 msec
Rotation time	200 msec	8.33 msec
Motor stop/start time	250 msec	20 sec
Time to transfer 1 sector	22 msec	17 μ sec

Disk parameters for the original IBM PC floppy disk and a Western Digital WD 18300 hard disk

Geometry of a Disk

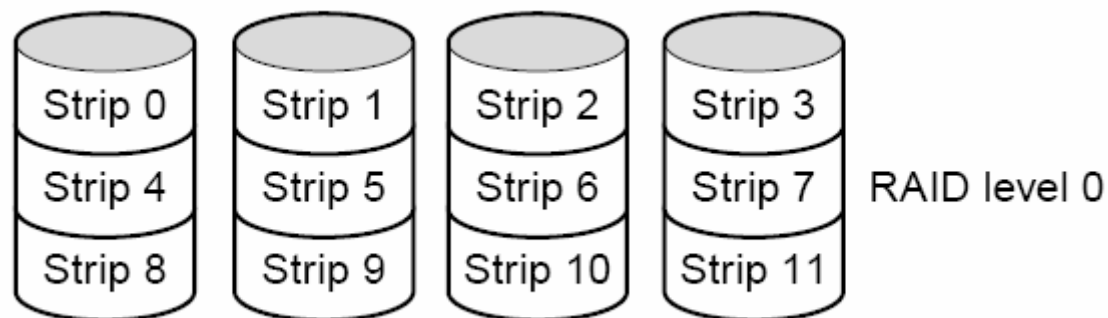


- Physical geometry of a disk with two zones
- A possible virtual geometry for this disk

RAID

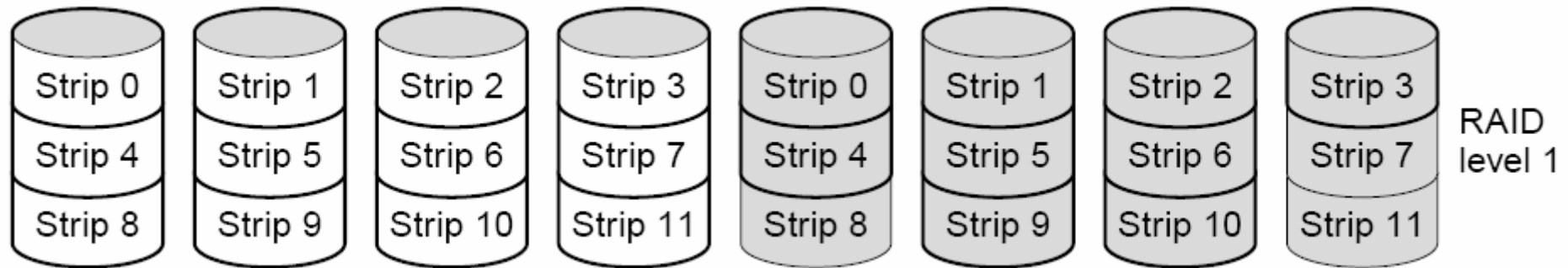
- **Parallel I/O might be a good idea to improve performance**
- **RAID**
 - **Redundant Array of Inexpensive Disks**
 - **Redundant Array of Independent Disks**
- **SLED**
 - **Single Large Expensive Disk**
- **Make a RAID to be looked like a SLED to the OS**

RAID 0



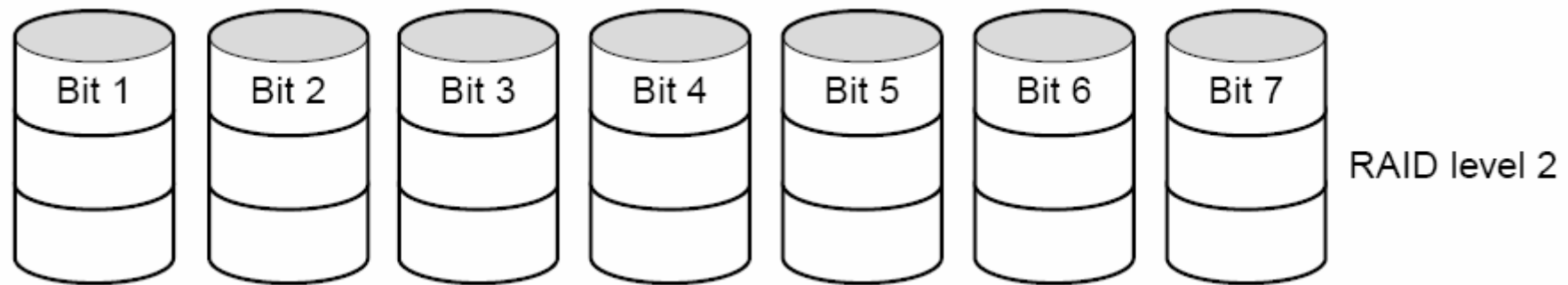
- Every strip has k sectors
- Works best with large requests
 - worst with asking for one sector at a time
- Reliability is worse than a SLED
- Uses all space, no redundancy

RAID 1



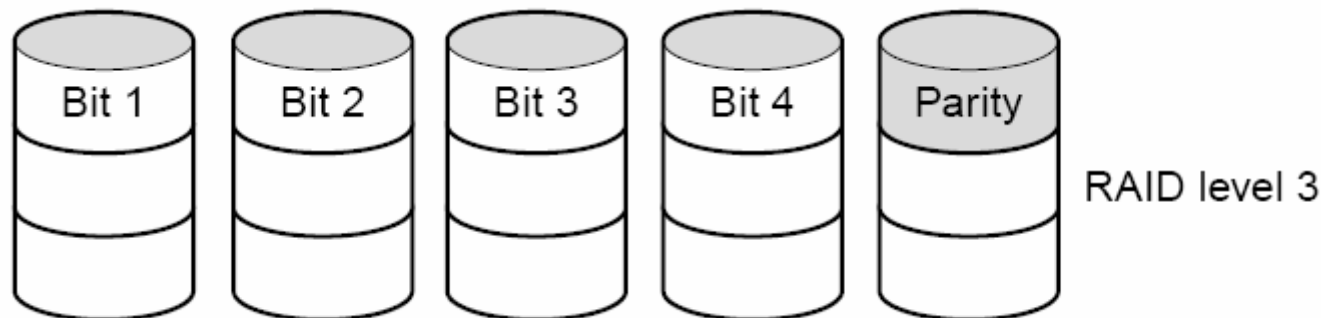
- There are the same number of backup disks as the primary disks
- Write performance is no better, but read performance is up to twice
- Fault tolerance is excellent

RAID 2



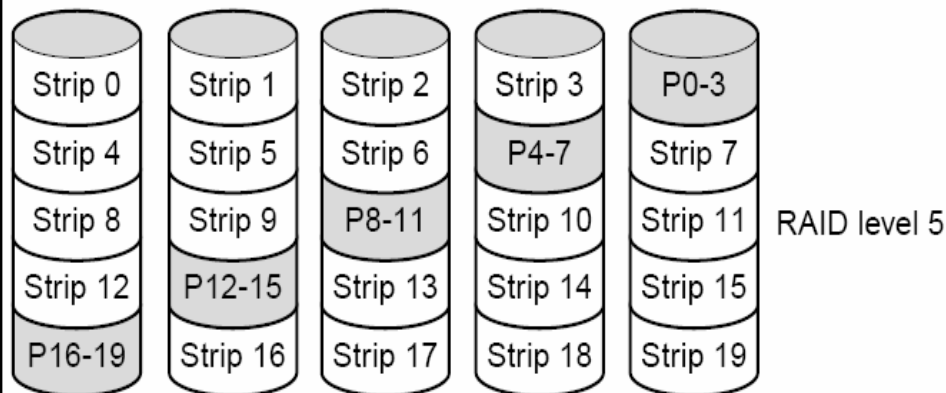
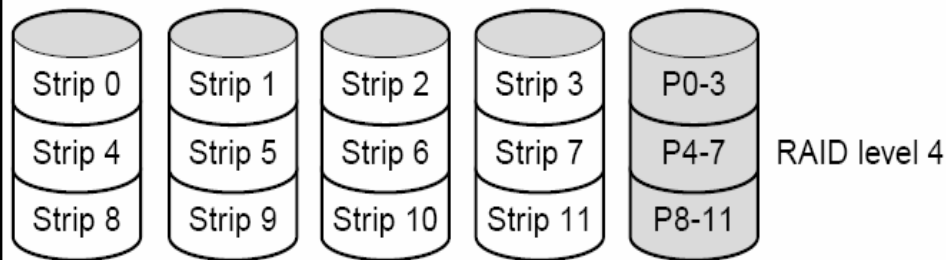
- Splits each byte into a pair of 4-bit nibbles
- Adds a Hamming code to each one to form a 7-bit word
- One bit per drive
- Also can 32-bit word with 6 parity bits to form a 38-bit Hamming word
- Losing one drive did not cause problems

RAID 3



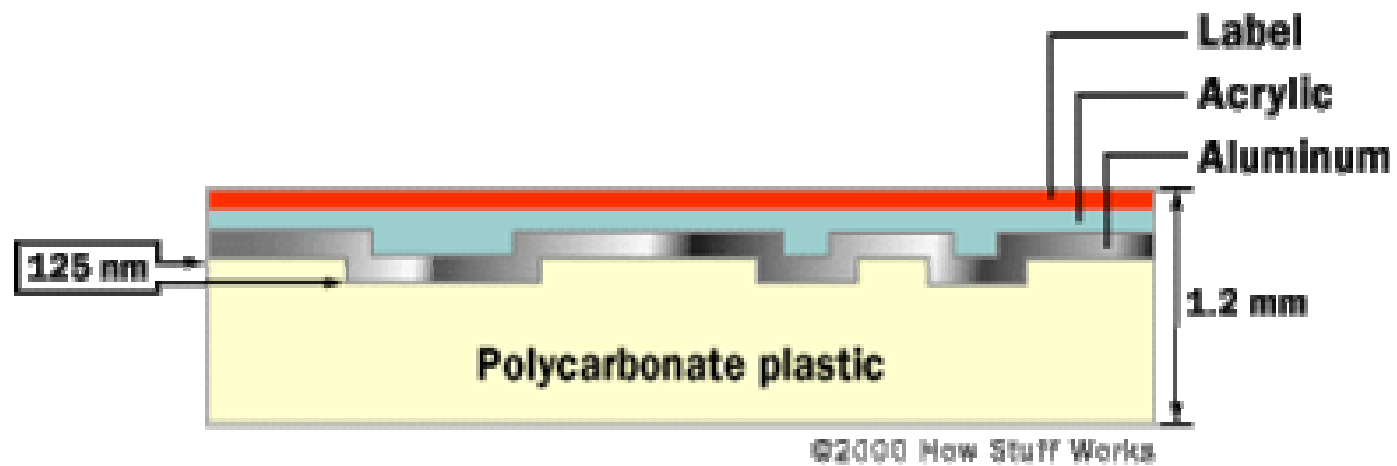
- A simplified version of RAID level 2
- A single parity bit is computed for each data word and written to a parity drive
- One drive crashing can be recovered

RAID 4 & 5

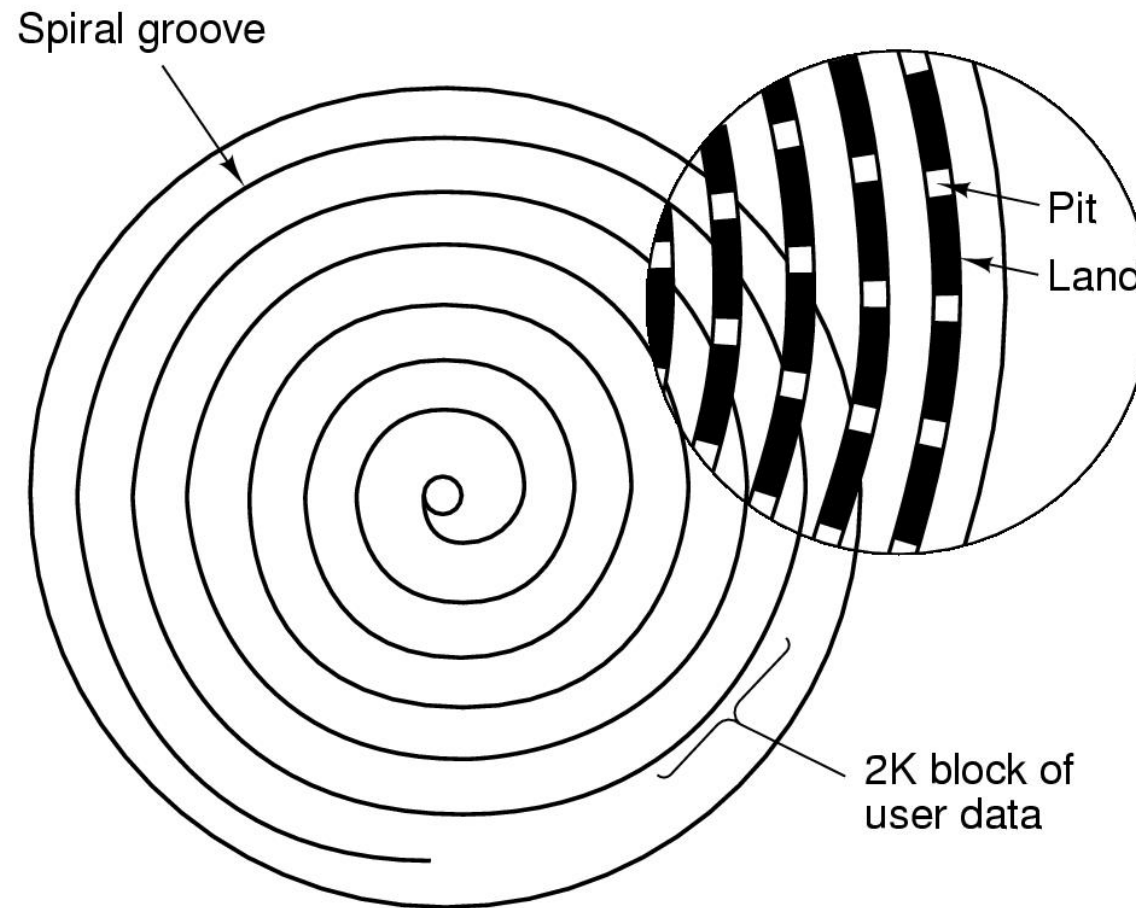


- All the strips are **EXCLUSIVE ORed** together to a parity strip
- Write performance is bad
- The parity drive in RAID 4 is bottleneck
- RAID 5 distributes the parity bits

CD-ROM

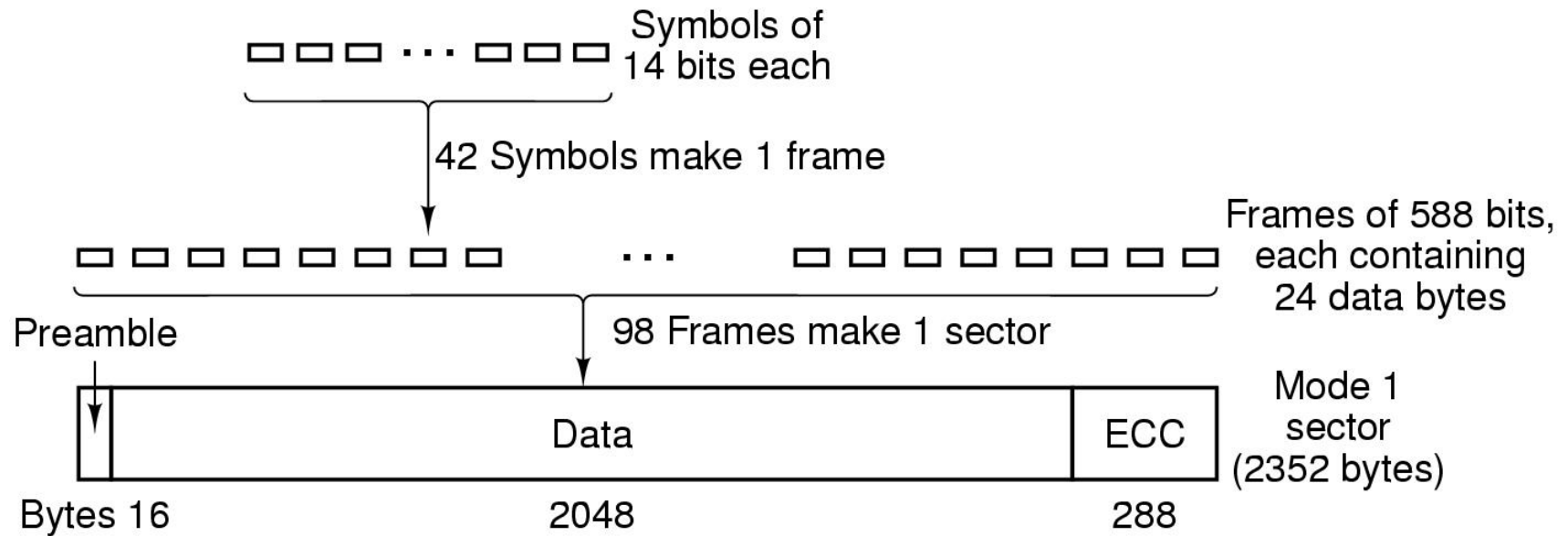


CD-ROM



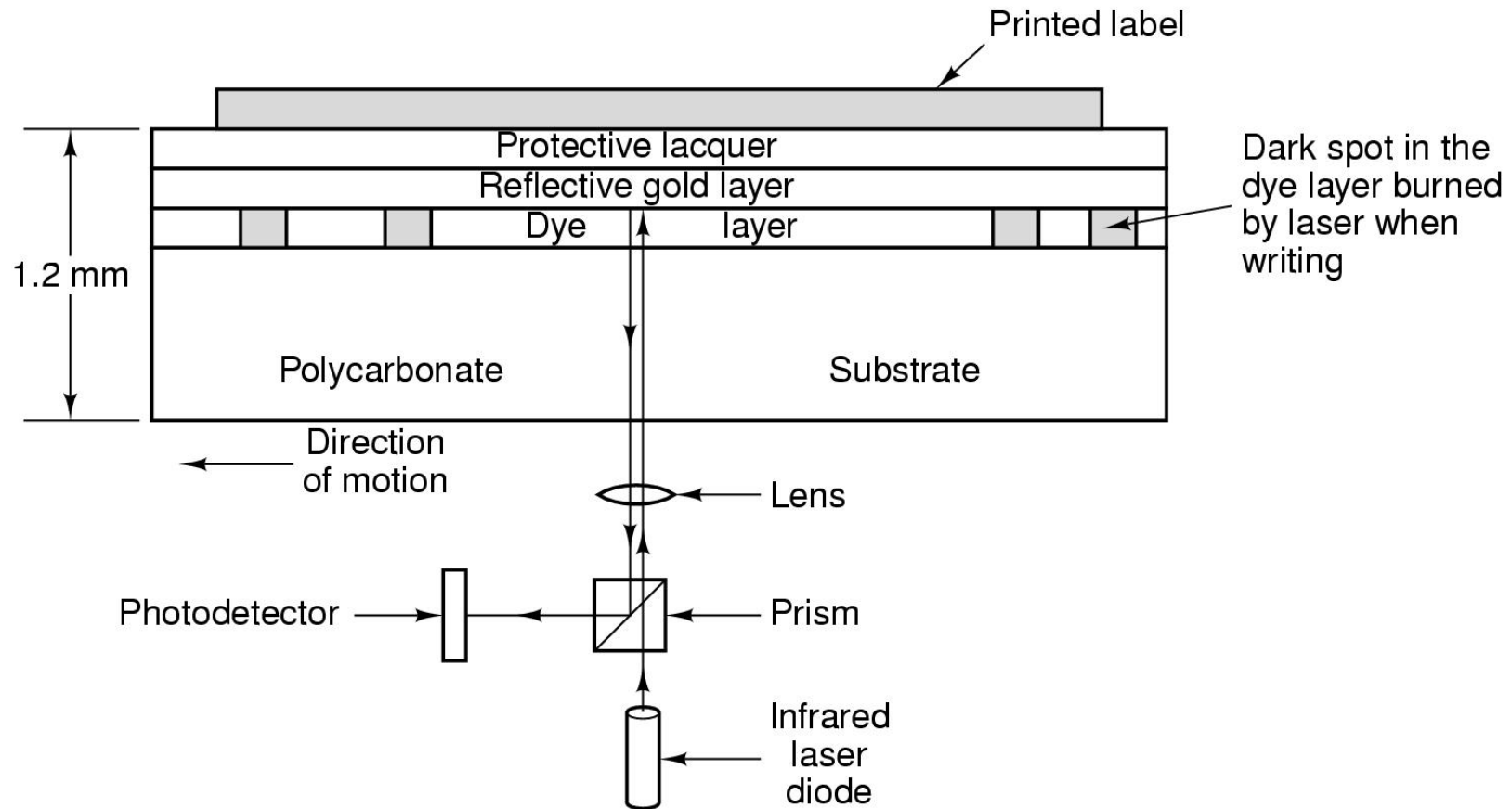
Recording structure of a CD or CD-ROM

CD-ROM

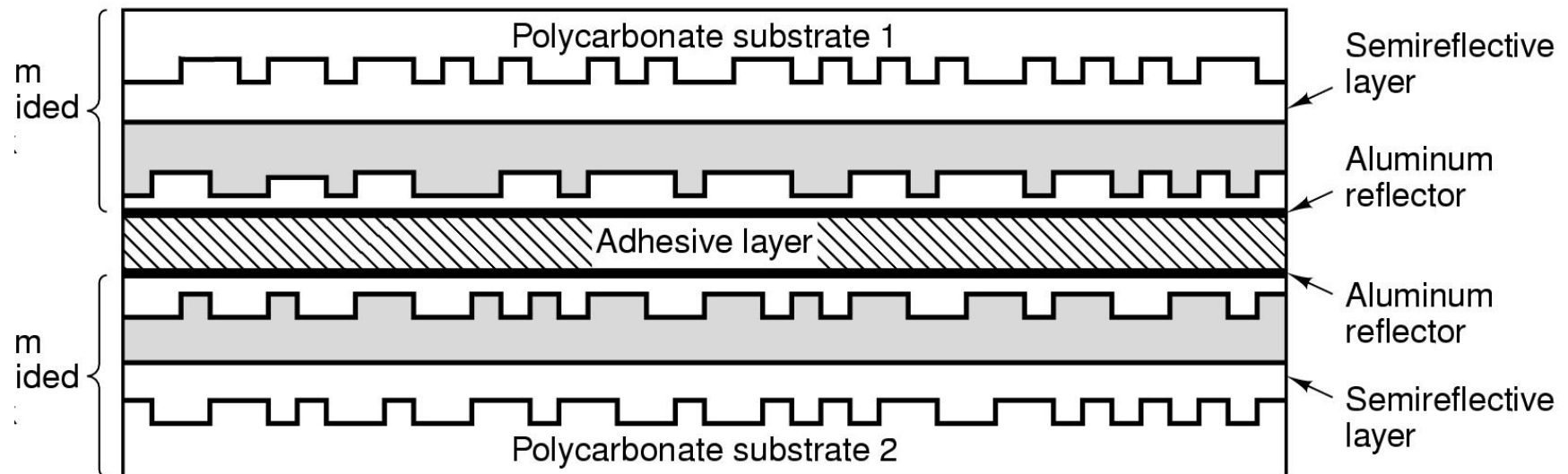


Logical data layout on a CD-ROM

CD-R



DVD



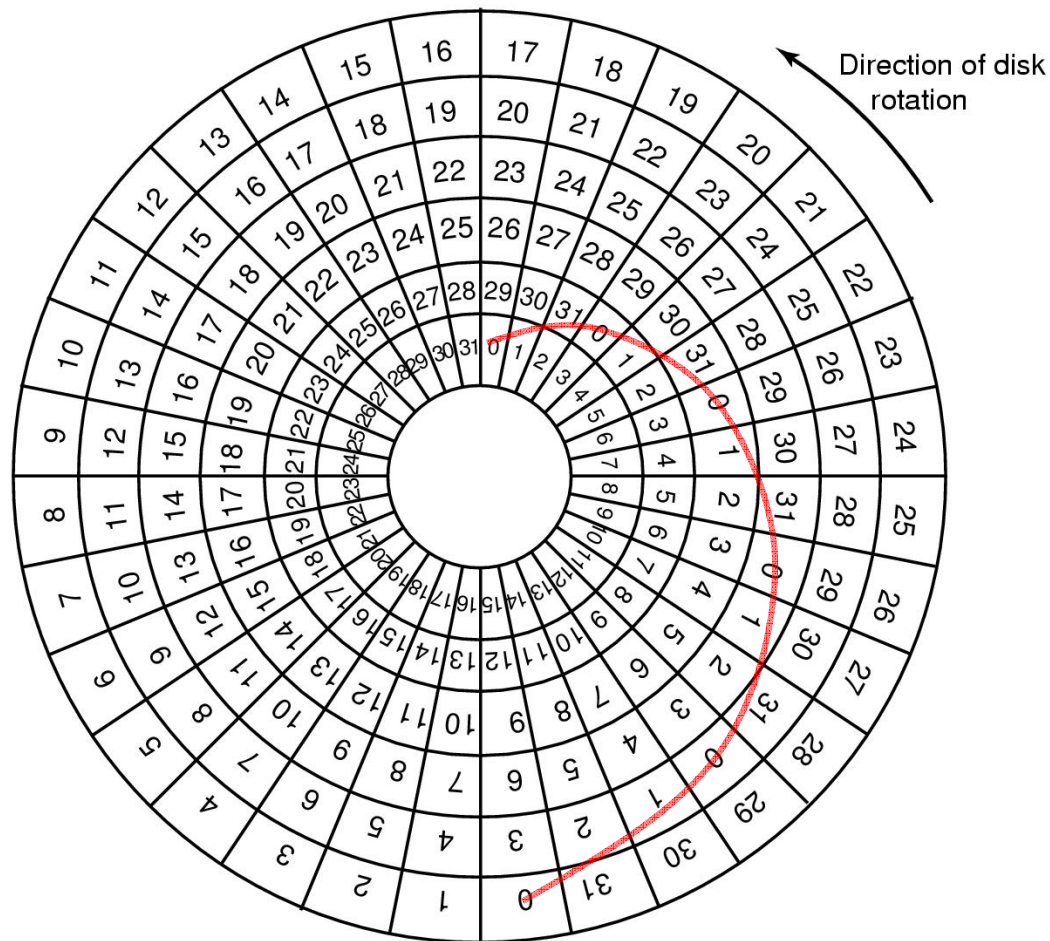
A double sided, dual layer DVD disk

Disk Formatting (1)



A disk sector

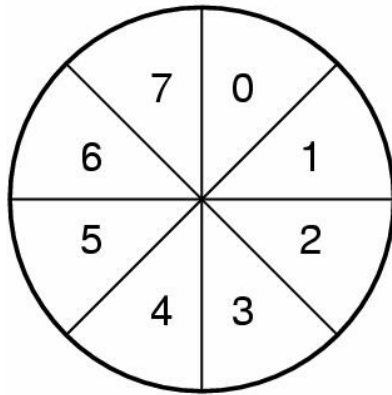
Disk Formatting (2)



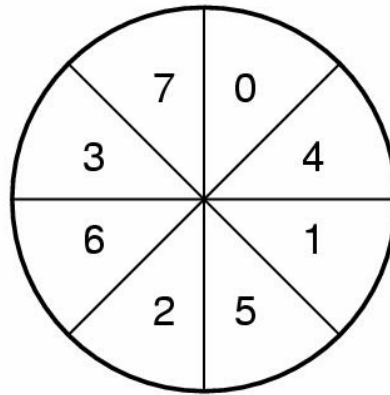
An illustration of cylinder skew

sun@hit.edu.cn

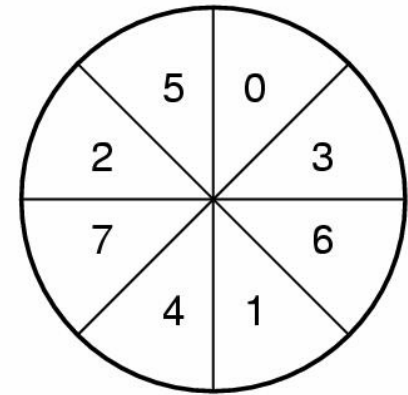
Disk Formatting (3)



(a)



(b)



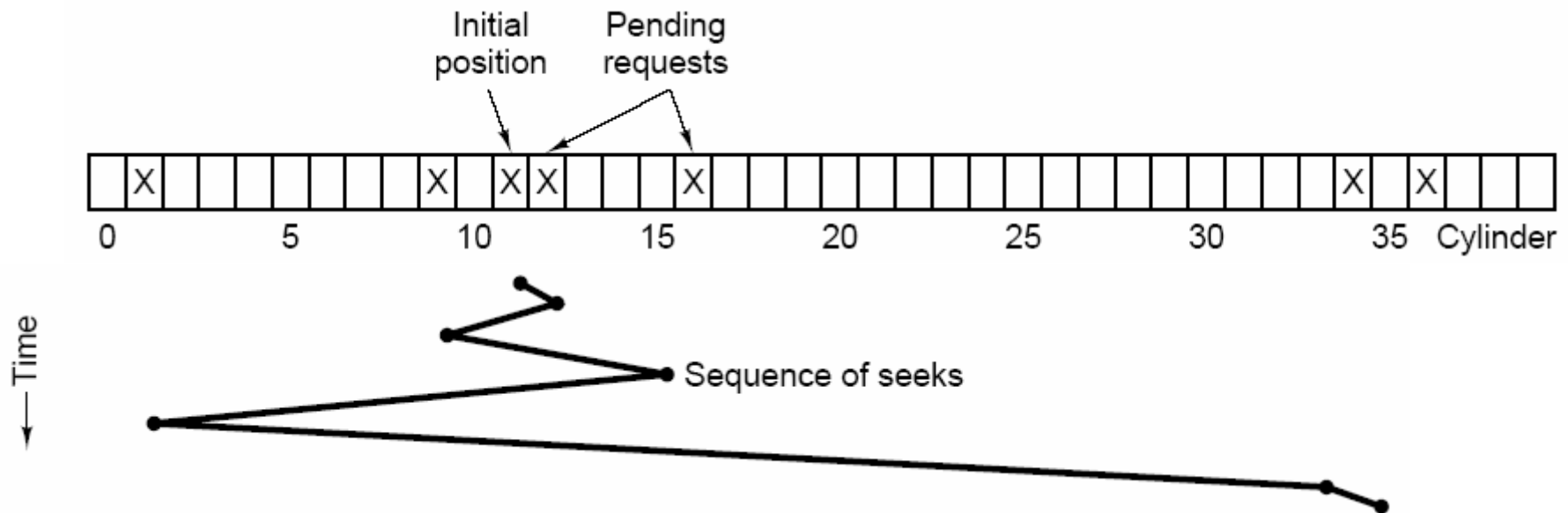
(c)

- No interleaving
- Single interleaving
- Double interleaving

Disk Arm Scheduling Algorithms

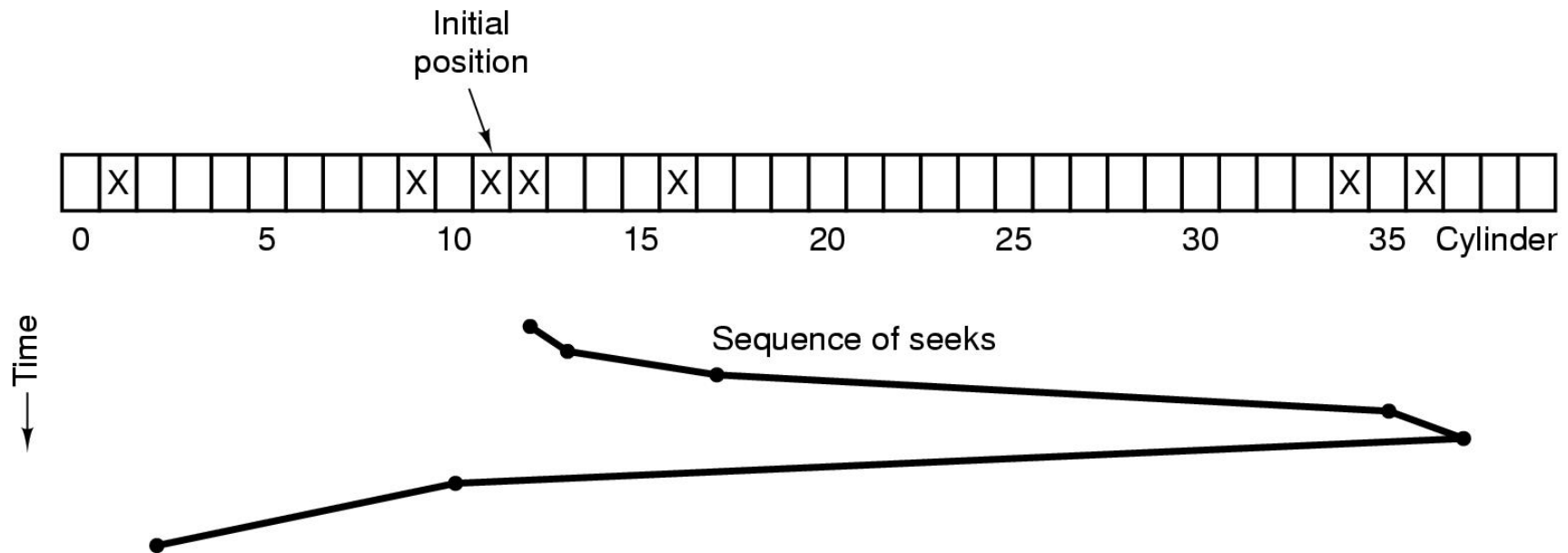
- Time required to read or write a disk block determined by 3 factors
 1. Seek time
 2. Rotational delay
 3. Actual transfer time
- Seek time dominates
- Error checking is done by controllers

Shortest Seek First (SSF) disk scheduling algorithm



Seek request: 11, 1, 36, 16, 34, 9 and 12

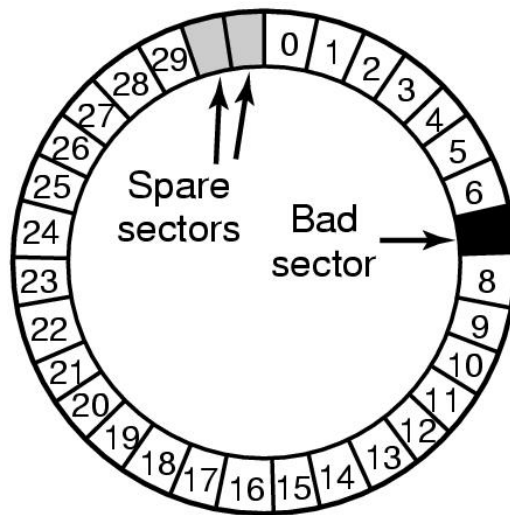
The elevator algorithm for scheduling disk requests



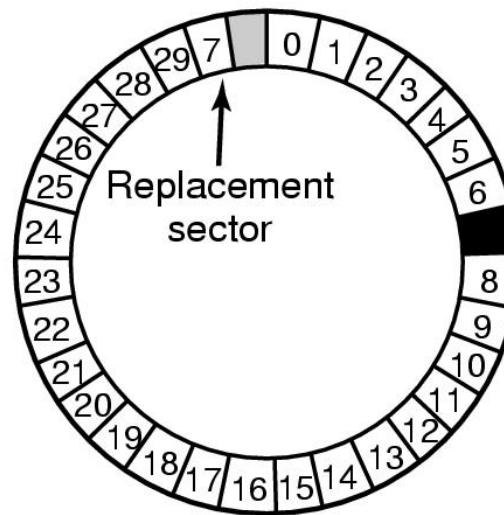
Error Handling

- Small defeat can be corrected by the ECC
- Bigger defeat
 - deal with them in the controller
 - deal with them in the OS

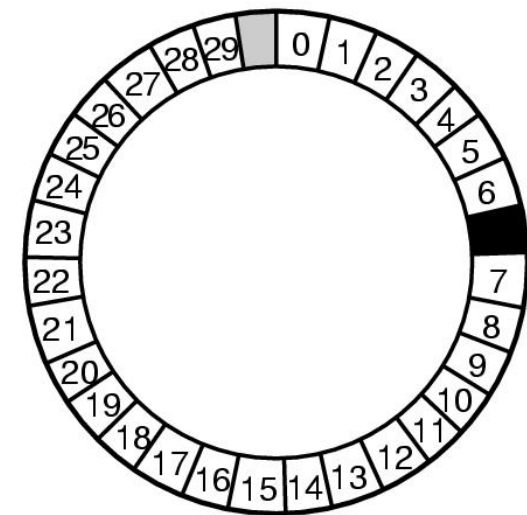
Error Handling in Controller



(a)



(b)

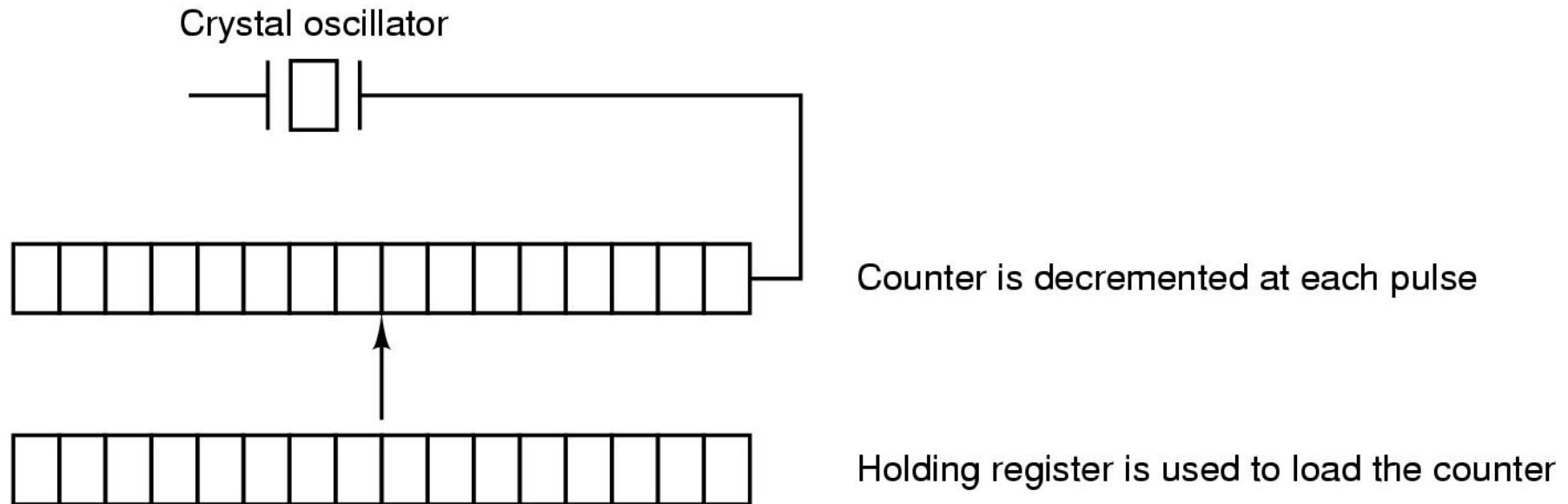


(c)

- A disk track with a bad sector
- Substituting a spare for the bad sector
- Shifting all the sectors to bypass the bad one

Clocks

Clock Hardware

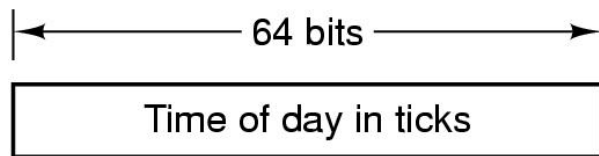


A programmable clock

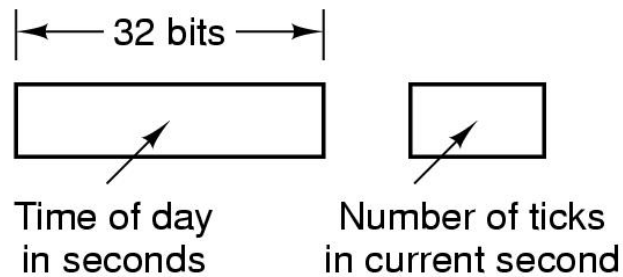
Clock Software

- Maintaining the time of day
- Preventing processes from running longer than they are allowed to
- Accounting for CPU usage
- Handling the alarm system call made by user processes
- Providing watchdog timers for parts of the system itself
- Doing profiling, monitoring, and statistics gathering

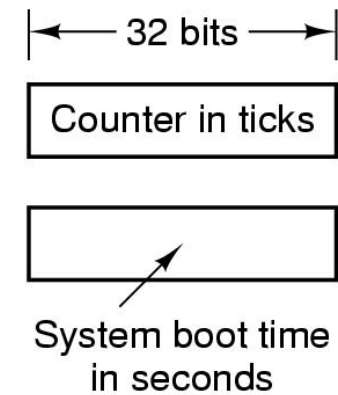
Maintaining the time of day



(a)



(b)

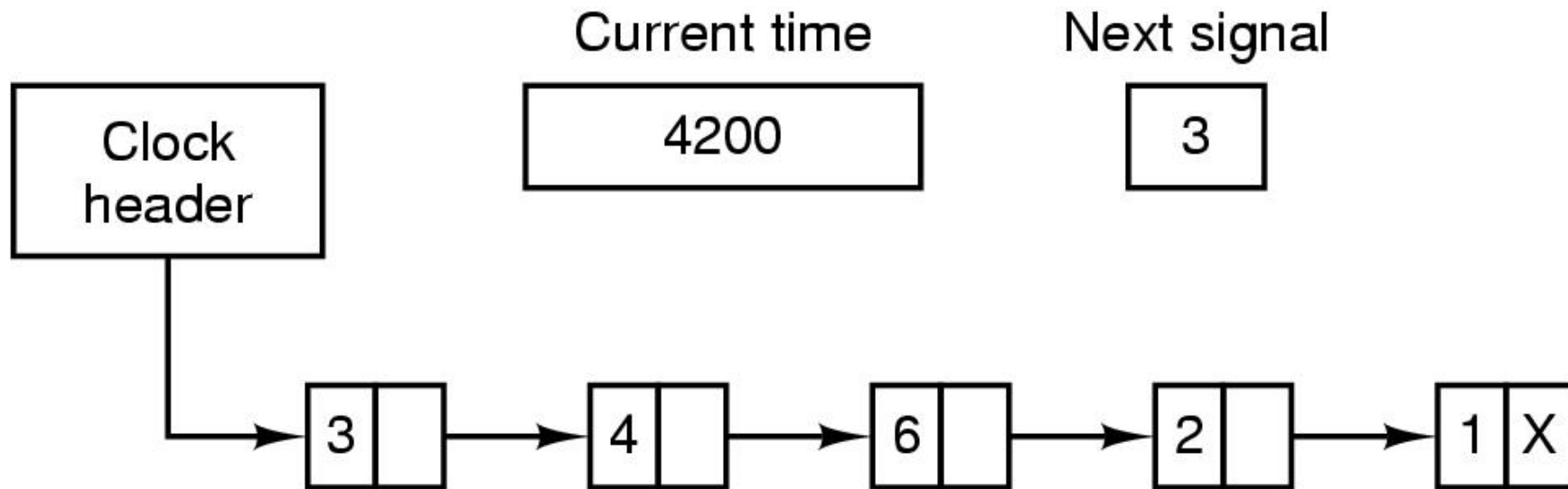


(c)

Clock Software

- **Preventing processes from running longer than they are allowed to**
 - decrement the quantum counter of running process by 1
- **Accounting for CPU usage**
 - use a second timer to count
 - count in the PCB

Handling the alarm system call made by user processes



- Simulating multiple timers with a single clock
- On each tick, *Next signal* is decremented

Clock Software

- **Providing watchdog timers for parts of the system itself**
 - **for kernel software such as drivers and etc.**
- **Doing profiling, monitoring, and statistics gathering**

Soft Timers

- **Soft timers avoid interrupts**
 - kernel checks for soft timer expiration before it exits to user mode
 - how well this works depends on rate of kernel entries
- **Kernel entries are made for reasons:**
 - system calls
 - TLB misses
 - page faults
 - I/O interrupts
 - the CPU going idle

Graphical User Interface (GUI)

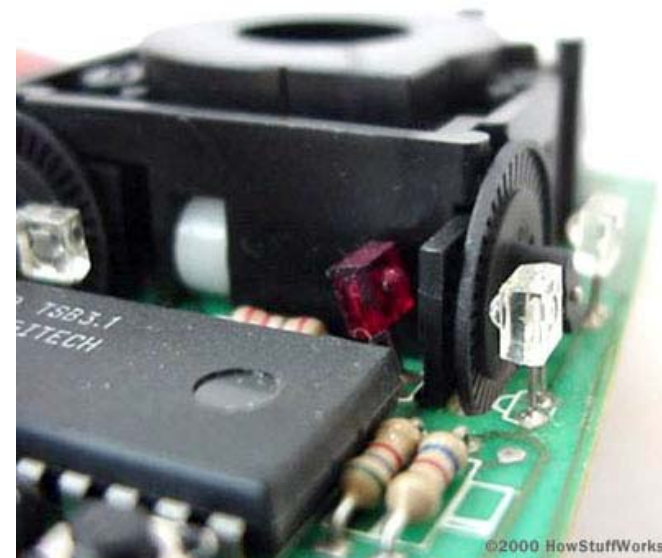
- **Invented by Douglas Engelbart and used by Steve Jobs**
- **WIMP**
 - **Windows Icons, Menus, and Pointing device**
- **Can be implemented in either user-level code or in the operating system itself**

Keyboard

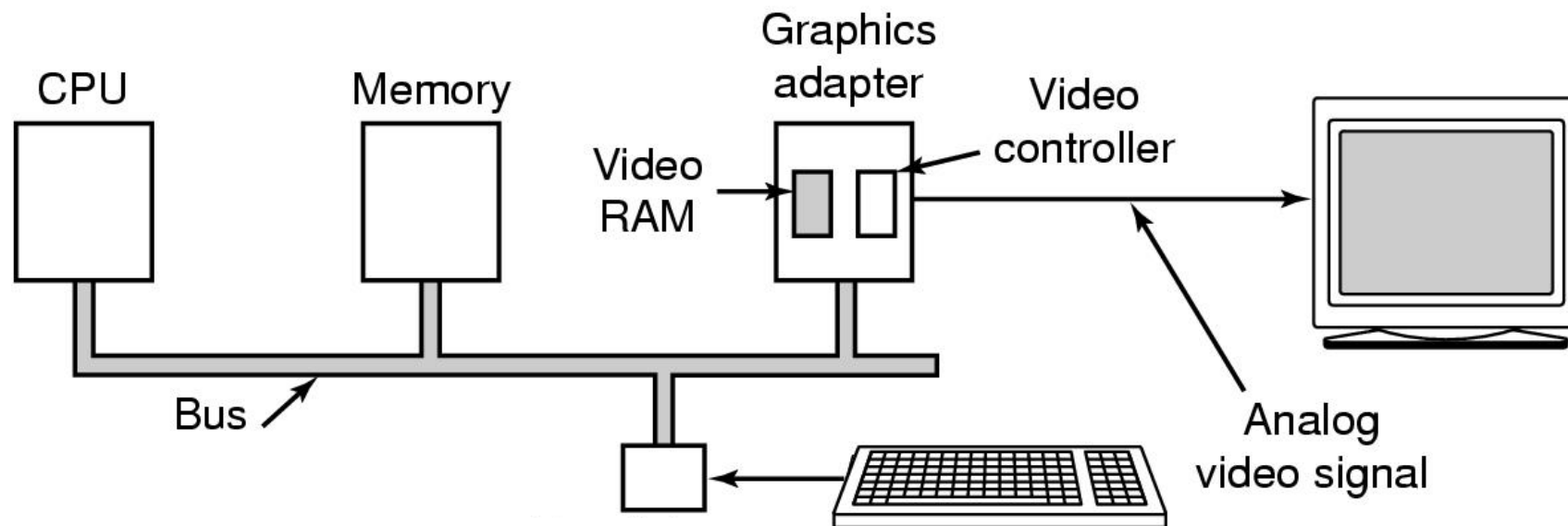
- All that the keyboard hardware provides is the key number, not the ASCII code
- An interrupt is generated whenever a key is struck or released
 - **DEPRESS SHIFT, DEPRESS A, RELEASE A, RELEASE SHIFT**
 - **DEPRESS SHIFT, DEPRESS A, RELEASE SHIFT, RELEASE A**

Mouse

- The messages sent by mice to the computer contains three items:
 - Δx , Δy , buttons
- Mouse only reports single click



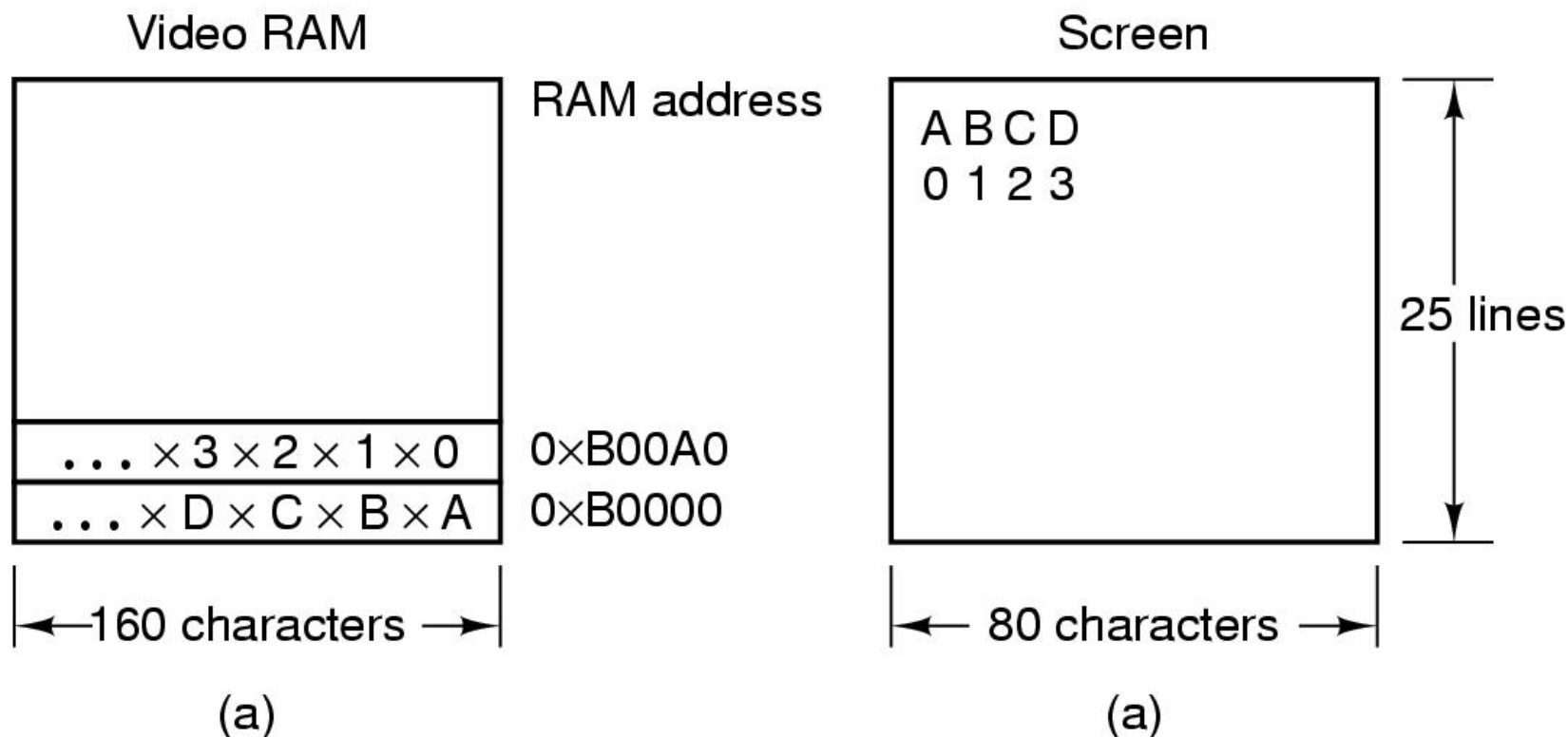
Display Hardware



Memory-mapped displays

- driver writes directly into display's video RAM

Monochrome Display

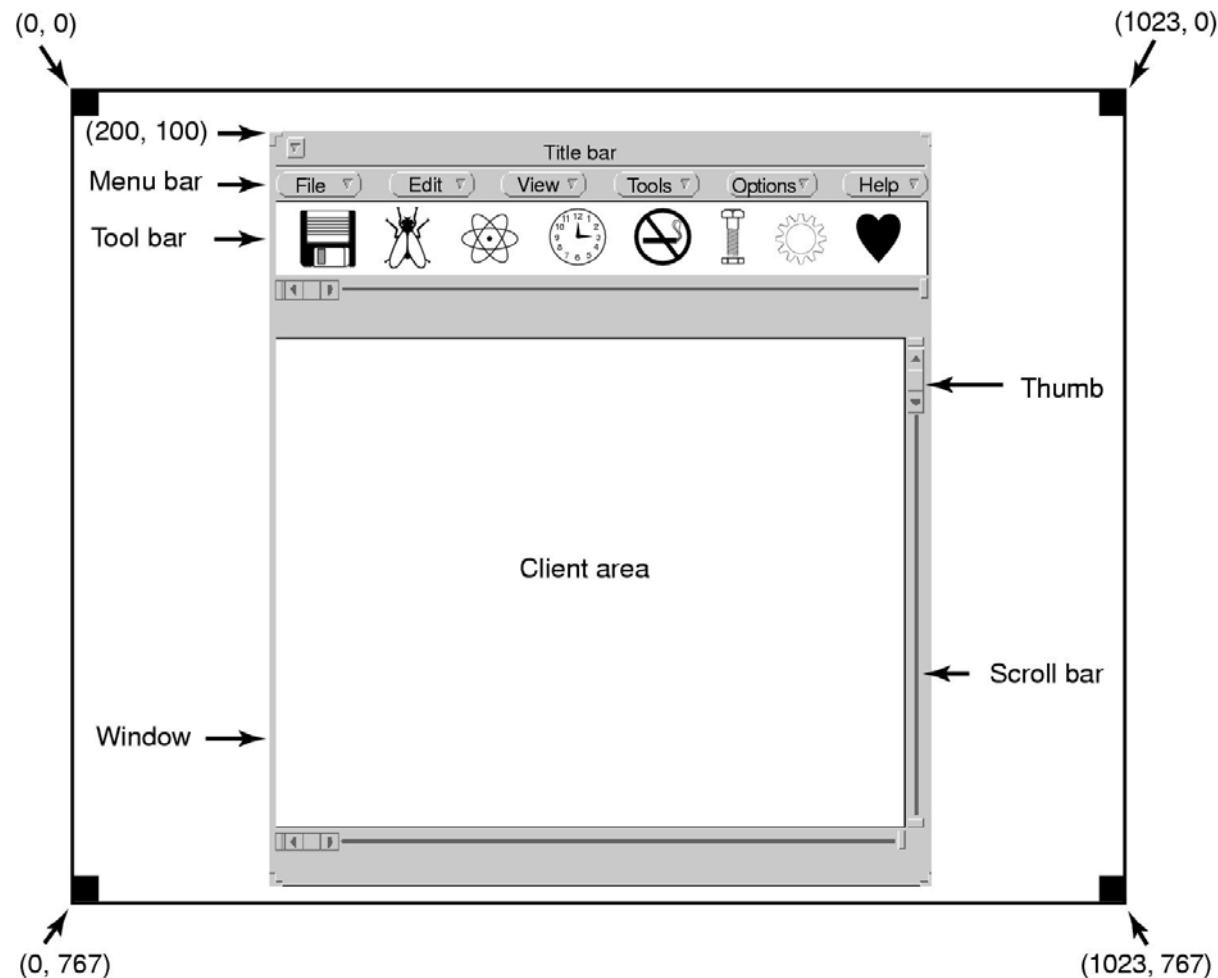


- A video RAM image
- Corresponding screen

Input Software

- **Keyboard driver delivers a number**
 - **driver converts to characters**
 - **uses a ASCII table**
- **Exceptions, adaptations needed for other languages**
 - **many OS provide for loadable keymaps or code pages**

Output Software for Windows



Sample window located at (200,100) on XGA display

Output Software for Windows

```
#include <windows.h>
```

```
int WINAPI WinMain(HINSTANCE h, HINSTANCE, hprev, char *szCmd, int iCmdShow)
{
    WNDCLASS wndclass;           /* class object for this window */
    MSG msg;                     /* incoming messages are stored here */
    HWND hwnd;                   /* handle (pointer) to the window object */

    /* Initialize wndclass */
    wndclass.lpfnWndProc = WndProc; /* tells which procedure to call */
    wndclass.lpszClassName = "Program name"; /* Text for title bar */
    wndclass.hIcon = LoadIcon(NULL, IDI_APPLICATION); /* load program icon */
    wndclass.hCursor = LoadCursor(NULL, IDC_ARROW); /* load mouse cursor */

    RegisterClass(&wndclass); /* tell Windows about wndclass */
    hwnd = CreateWindow ( ... ) /* allocate storage for the window */
    ShowWindow(hwnd, iCmdShow); /* display the window on the screen */
    UpdateWindow(hwnd); /* tell the window to paint itself */
}
```

Skeleton of a Windows main program (part 1)

Output Software for Windows

```
while (GetMessage(&msg, NULL, 0, 0)) { /* get message from queue */
    TranslateMessage(&msg); /* translate the message */
    DispatchMessage(&msg); /* send msg to the appropriate procedure */
}
return(msg.wParam);
}

long CALLBACK WndProc(HWND hwnd, UINT message, UINT wParam, long lParam)
{
    /* Declarations go here. */

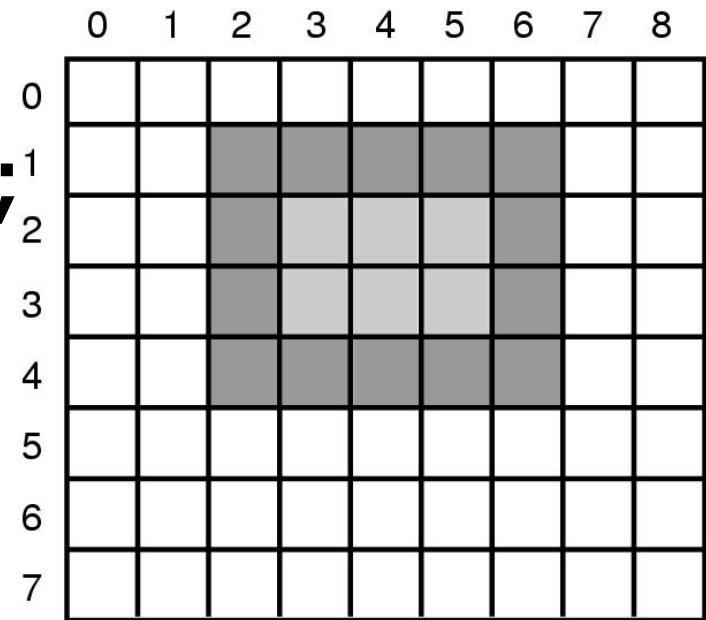
    switch (message) {
        case WM_CREATE:    ... ; return ... ; /* create window */
        case WM_PAINT:     ... ; return ... ; /* repaint contents of window */
        case WM_DESTROY:   ... ; return ... ; /* destroy window */
    }
    return(DefWindowProc(hwnd, message, wParam, lParam)); /* default */
}
```

Skeleton of a Windows main program (part 2)

GDI

(Graphical Device Interface)

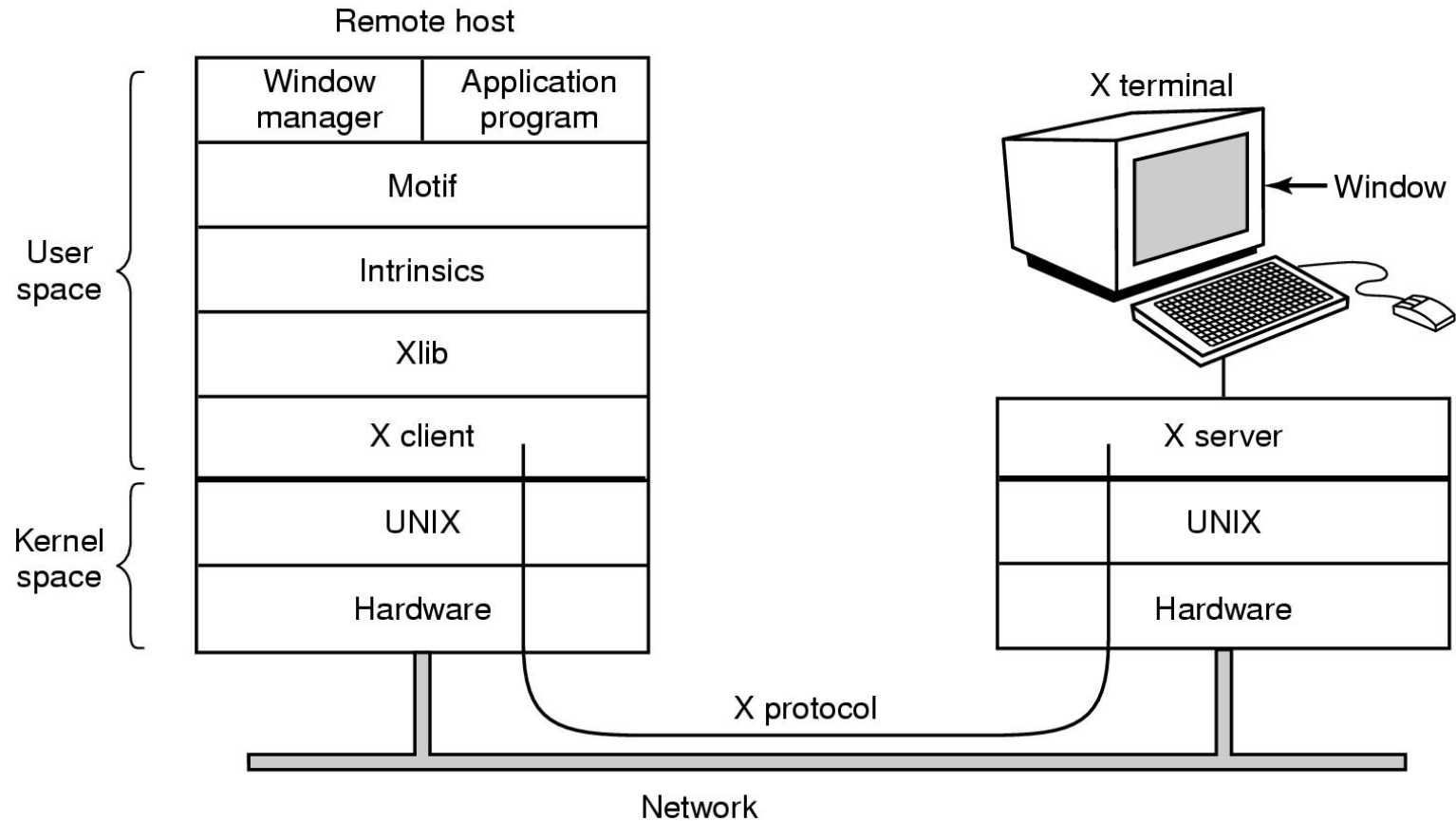
- `hdc = GetDC(hwnd);`
`TextOut(`
 `hdc, x, y,`
 `psText, iLength);`
`ReleaseDC(`
 `hwnd, hdc);`



- `Rectangle(hdc, 2, 1, 6, 4)`

Network Terminals

X Windows



Clients and servers in the M.I.T. X Window System

Skeleton of an X Windows Application Program

```
#include <X11/Xlib.h>
#include <X11/Xutil.h>

main(int argc, char *argv[])
{
    Display disp;                /* server identifier */
    Window win;                  /* window identifier */
    GC gc;                       /* graphic context identifier */
    XEvent event;                /* storage for one event */
    int running = 1;

    disp = XOpenDisplay("display_name");    /* connect to the X server */
    win = XCreateSimpleWindow(disp, ... );    /* allocate memory for new window */
    XSetStandardProperties(disp, ...);        /* announces window to window mgr */
    gc = XCreateGC(disp, win, 0, 0);          /* create graphic context */
    XSelectInput(disp, win, ButtonPressMask | KeyPressMask | ExposureMask);
    XMapRaised(disp, win);                  /* display window; send Expose event */
}
```

Skeleton of an X Windows Application Program

```
while (running) {  
    XNextEvent(disp, &event); /* get next event */  
    switch (event.type) {  
        case Expose:      ...; break; /* repaint window */  
        case ButtonPress: ...; break; /* process mouse click */  
        case Keypress:    ...; break; /* process keyboard input */  
    }  
}  
  
XFreeGC(disp, gc); /* release graphic context */  
XDestroyWindow(disp, win); /* deallocate window's memory space */  
XCloseDisplay(disp); /* tear down network connection */  
}
```